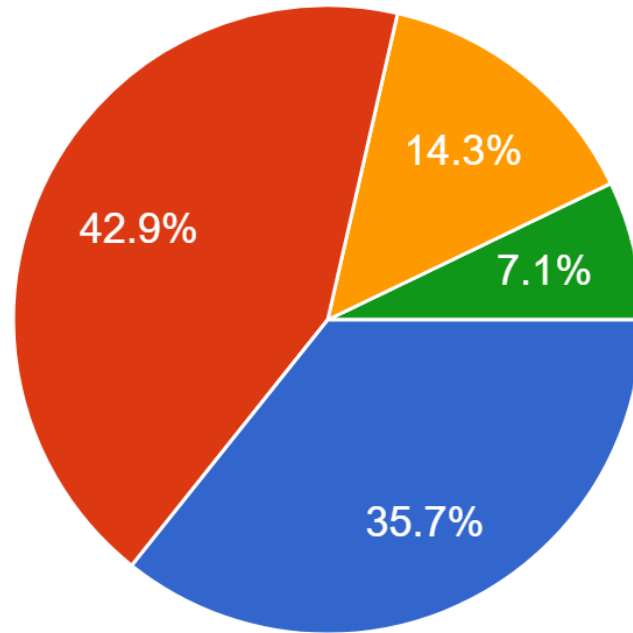


Survey overview

Microcontroller skills (say Arduino/Raspberry Pi)

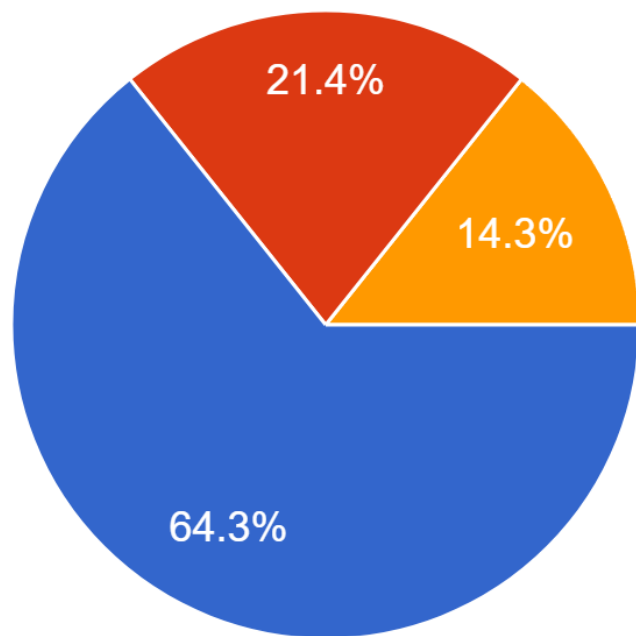
14 responses



- None.
- I tried it before but not very comfortable with it.
- Plenty of experience.
- Tech guru!

Laser cutter experience?

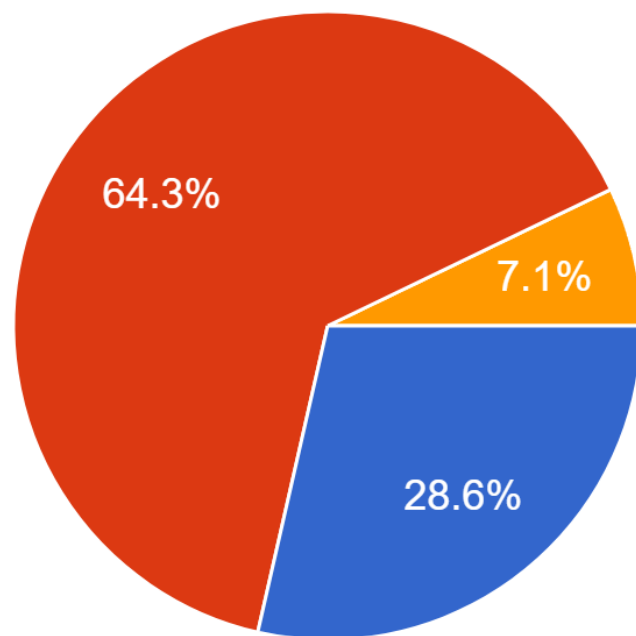
14 responses



- None.
- A little.
- Plenty.
- I use it all the time!

3D modeling experience?

14 responses



- None.
- Some.
- Plenty.
- I'm a master!

What do you want to learn from this course?

I want to do something cool with tangible objects and AR

I want to build a robot I'm proud of (given that I have 0 experience right now)

I want to learn more about combining hardware and software and do something with it.

I want to learn how to use a 3D printer

More about HCI and robotics

Trying to build some cool gadget and learn about what kind of cool stuff is being worked on.

I have already fulfilled all my course requirements. I am taking this course simply because it is super cool. I love robot stuff but I am purely plain on this background. I have done some UAV wise system research (simulation only), but I have not handed on any real robots yet.

I want to learn more application in HCI. I took AR class last semester and I think it is fun, so I want to delve more into AR/VR/XR. I also want to challenge myself to do sth cool rather than keep staying in the comfort zone designing only digital user interfaces.

Concerns that you would like to share with me?

My experience is mostly in software and I'm concerned that I may not have all the necessary skills to succeed in this course.

The biggest concern is this course may take too much of my time, though it must be fun. Next it could be.... I'm not sure if I can think up a cool "semester long project" idea, which should use very simple robots (not Boston Dynamics) to do very handful jobs...

Designing and building physical "things" that actually work well has always been something I've struggled with. I am fine with coding the devices but the hands-on physical engineering is not something I've typically done well with.

I am concerned about the semester project since I know how hard it can be to procure hardware sometimes. I am worried that it can end up being a last minute thing since procurement of parts and materials is often a challenge. In my lab I have seen how supply chain issues and department procurement issues can cripple progress on projects that have a hardware component.

I don't know anything about arduino 😅

Sources for ordering project related components.

[Adafruit.com](https://adafruit.com) (a great website as a "one-stop" shopping site)

[Sparkfun.com](https://sparkfun.com) (another great starting point to buy various electronic components)

[Pololu.com](https://pololu.com) (especially good for all kinds of motors)

[Hobbyking.com](https://hobbyking.com) (another website for shopping motors, especially drone-related motors such as servo/brushless motors)

[Robotshop.com](https://robotshop.com) (Motors + robot-related hardware)

[Mcmaster.com](https://mcmaster.com) (screws, pipe, foam sheet, acrylics, etc)

[Amazon.com](https://amazon.com) (this one you know for sure)

[Ebay.com](https://ebay.com) (you may find some very interesting items that are not easy to find in the US -> ; warning can be delayed!)

A person with glasses is shown in profile, gesturing with their hands while speaking. The background is a solid red color, and the lighting is dim, creating a focused atmosphere. The person is wearing a dark shirt and glasses.

Multi-touch Technology

Huaishu Peng | UMD CS | Fall 2024

JEFF**HAN**



How would you BUILD a
multi-touch devices?

JEFF**HAN**



How will you **track** the finger?
With what **hardware**?

JEFFHAN

1 min brainstorming

Draw some **sketches?**

There are lots of different

Type of technologies

Camera-based

Resistive

Capacitive ...

Let's review the **history** again...

Steve Jobs, 2007:

“And we have invented
a new technology
called multi-touch,
which is phenomenal.
[0:33:33]





1986: Sensor Frame (McAvinney)

but there is **tech close to multi-touch**
that actually was invented even earlier...

THESIS AT M.I.T.

LINCOLN LABS

FEB. 1963

Ivan Sutherland Demos Sketchpad, **1963**

we have come a long way since then...

30 years later, multi-touch has reached the consumer market...



and then there's still stuff
that **hasn't reached the consumer market yet**



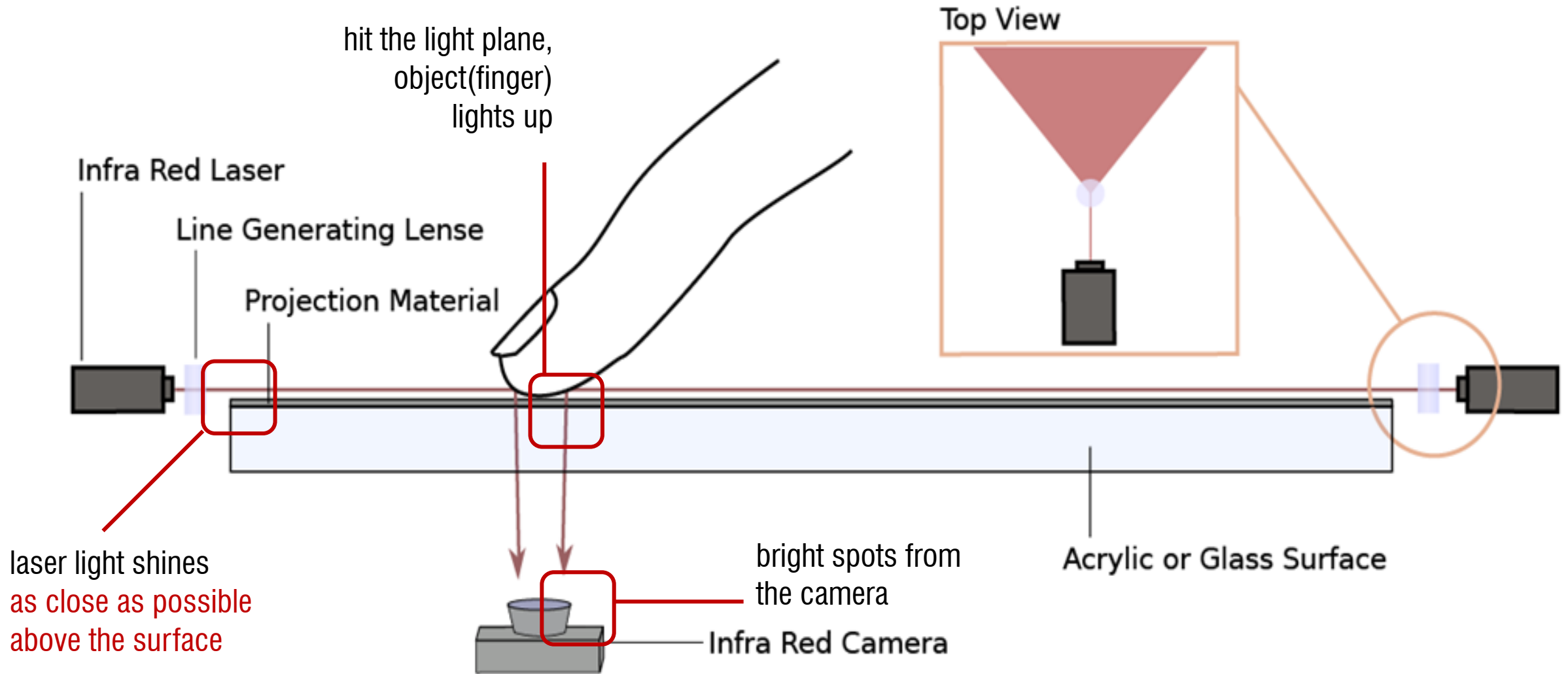
1991: Pierre Wellner, Digital Desk

multi-touch:
engineering principles

camera based multi-touch technology

#1 - Laser Light Plane (LLP)

LLP - Laser Light Plane



How does this recognize touch?

30s brainstorming

<http://sethsandler.com/multitouch/llp/>

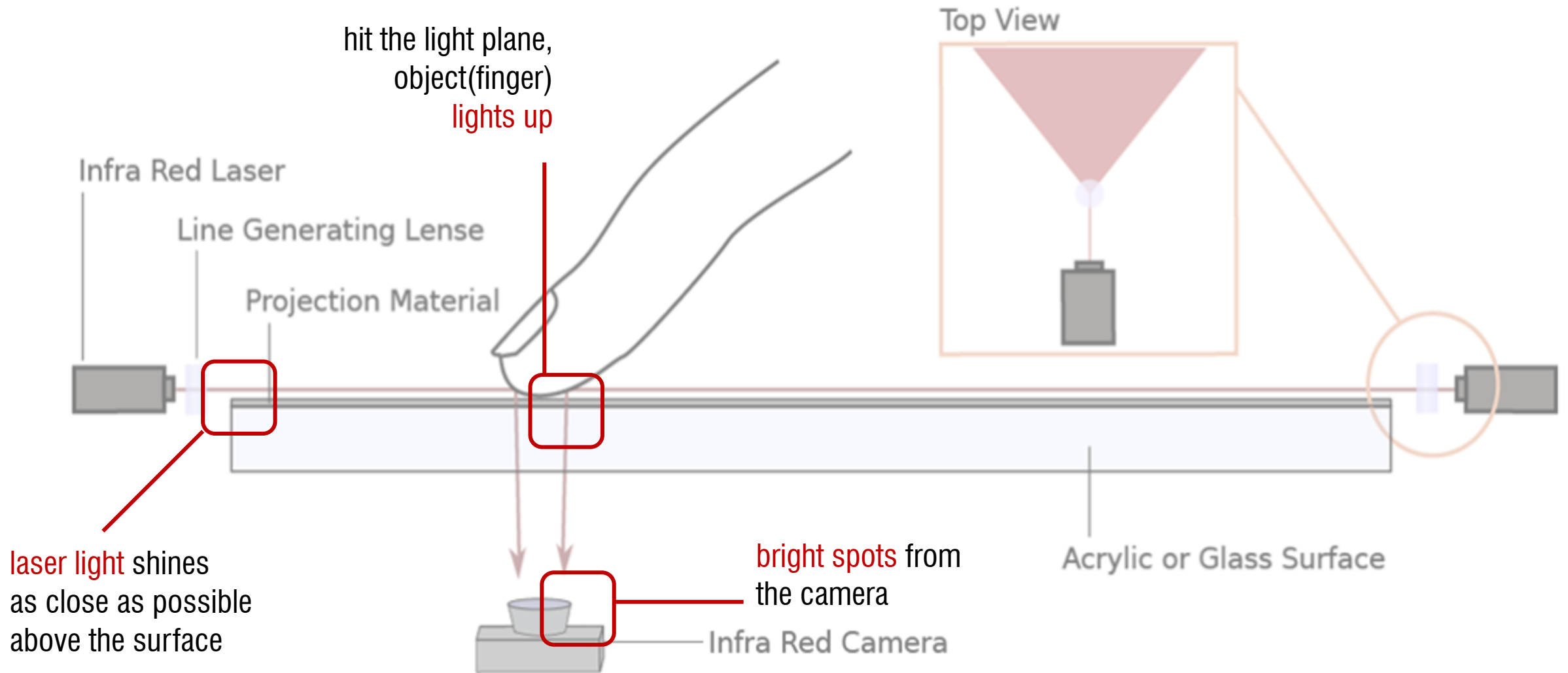


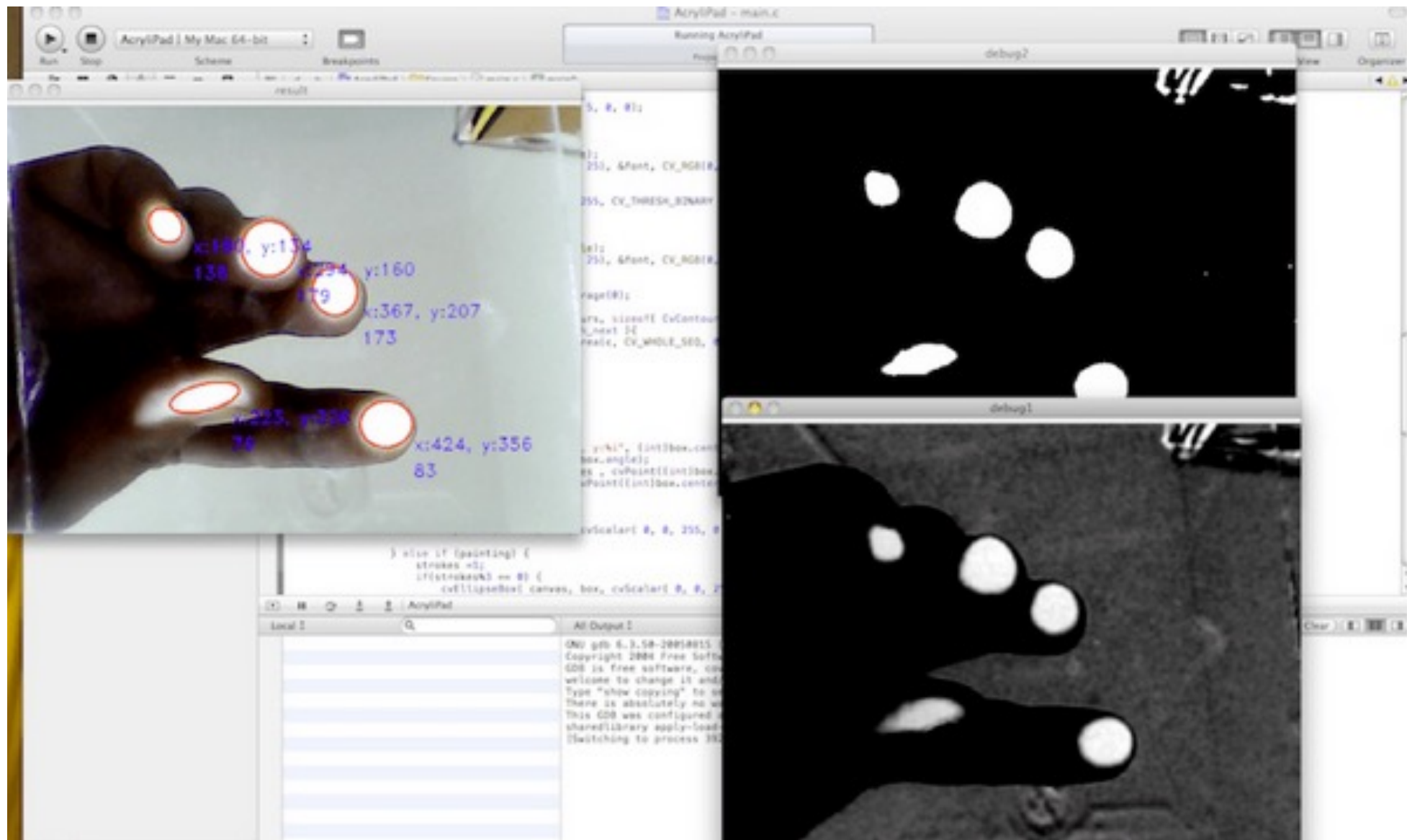
<http://www.youtube.com/watch?v=-GcmD0H8ebw>



<https://www.youtube.com/watch?v=mliHstoD4iU>

LLP - Laser Light Plane





easy to do computer vision tracking based on this

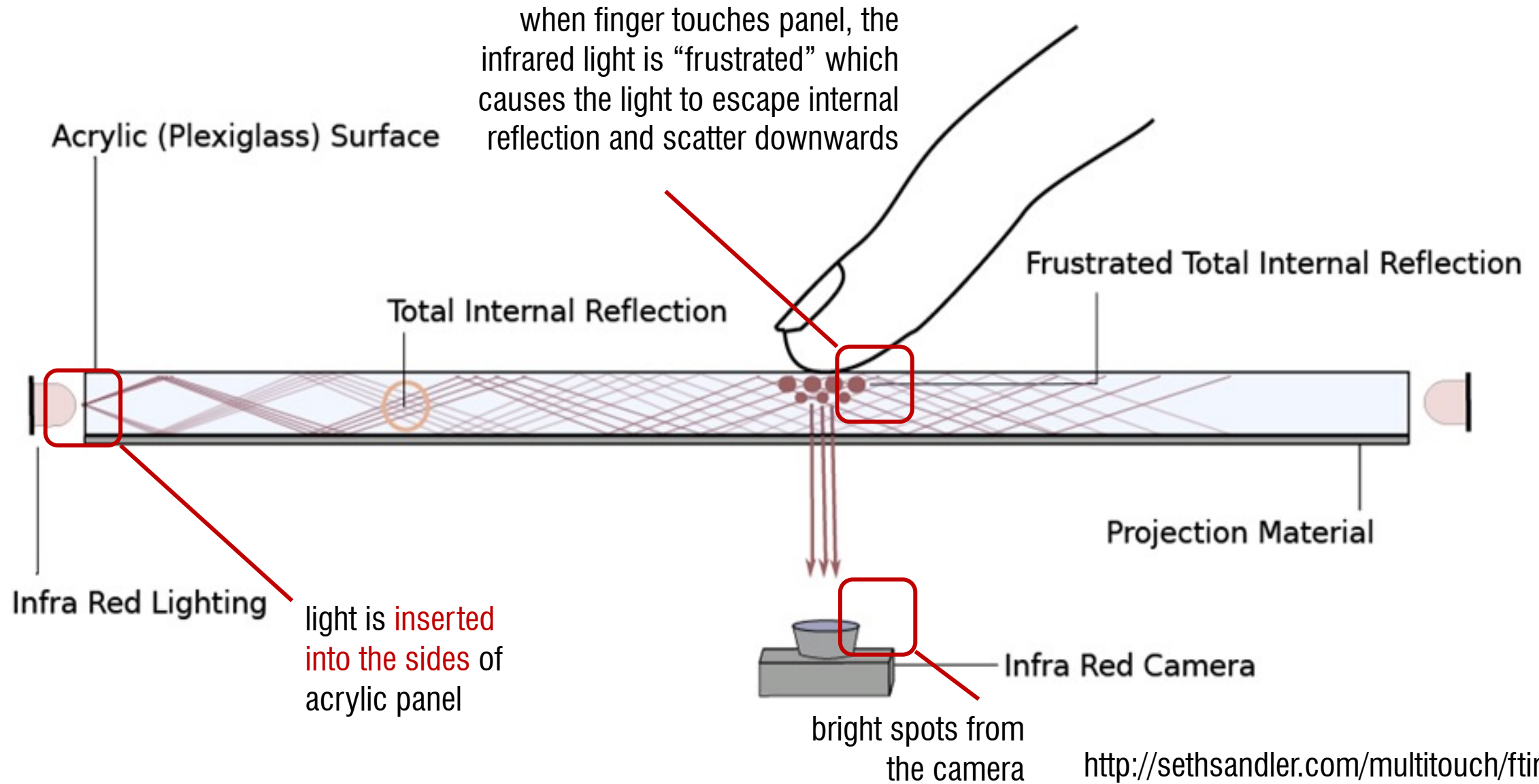
camera based multi-touch technology

#2 - frustrated total internal reflection

total internal reflection



FTIR - Frustrated Total Internal Reflection

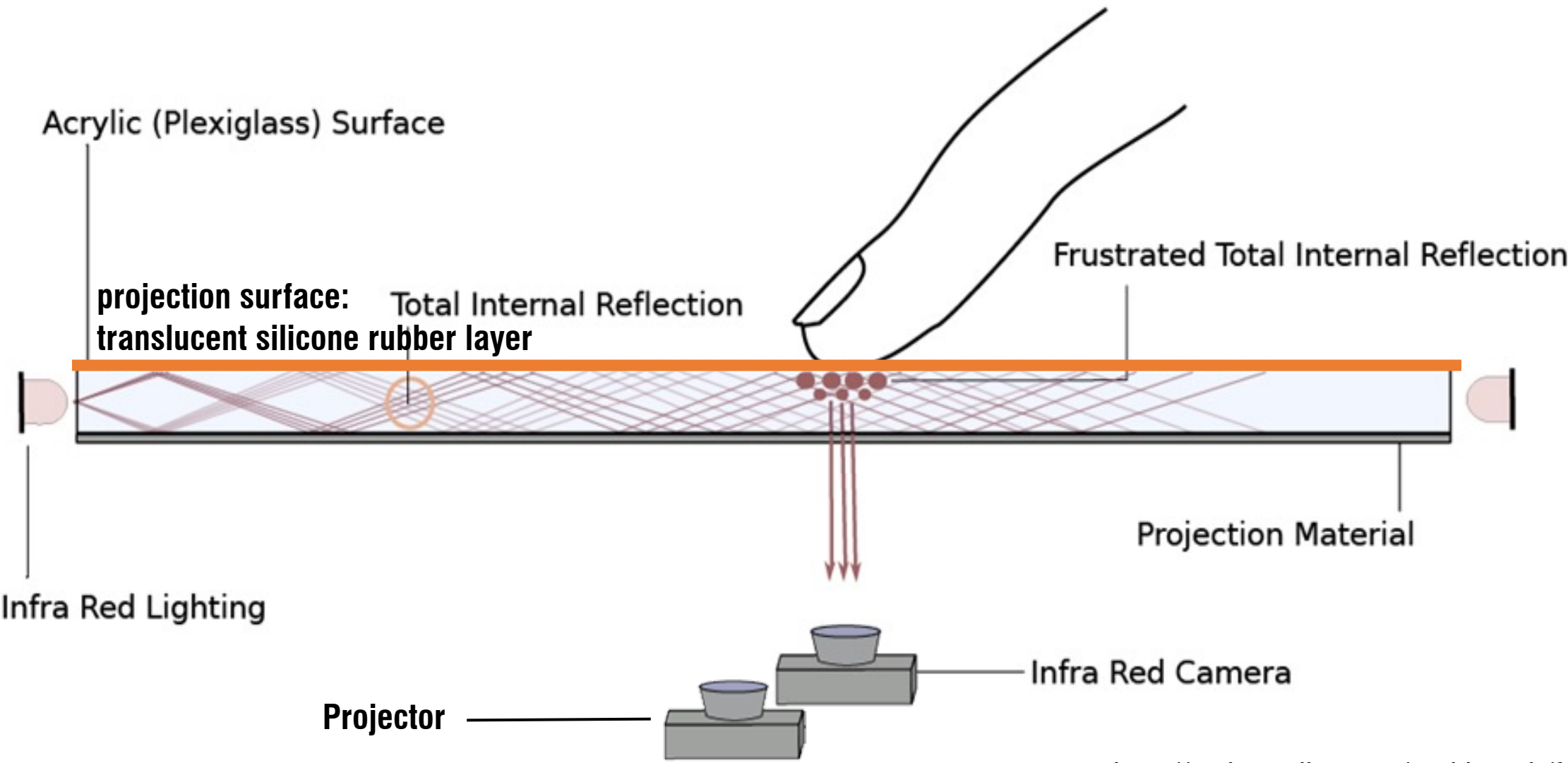


camera based multi-touch technology

#2 - frustrated total internal reflection
- combine with projector

since acrylic is transparent, you cannot directly project on it
add a projection surface allows to display an image

FTIR - Frustrated Total Internal Reflection



A man with glasses and a dark shirt is speaking at a podium. He is gesturing with his hands. The background is a solid red color. The name 'JEFFHAN' is displayed in white text at the bottom of the image.

JEFFHAN

Low-Cost Multi-Touch Sensing through Frustrated Total Internal Reflection

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Media Research Laboratory
New York University
719 Broadway, New York, NY 10003
E-mail: jhan@mrl.nyu.edu

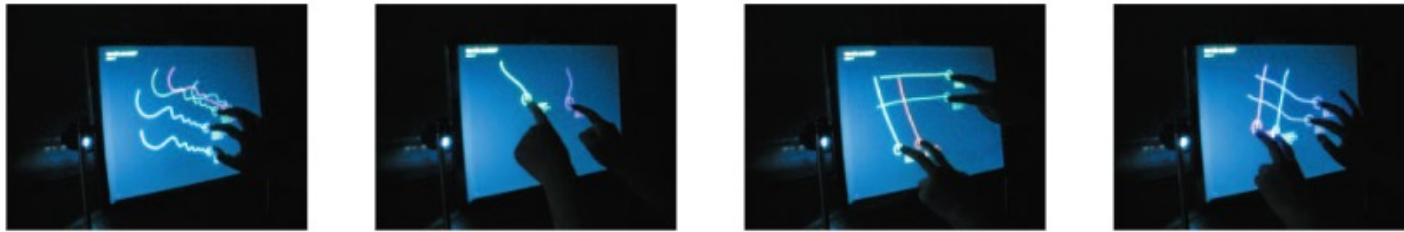


Figure 1: Simple examples of multi-touch interaction using our FTIR technique

ABSTRACT

This paper describes a simple, inexpensive, and scalable technique for enabling high-resolution multi-touch sensing on rear-projected interactive surfaces based on *frustrated total internal reflection*. We review previous applications of this phenomenon to sensing, provide implementation details, discuss results from our initial prototype, and outline future directions.

ACM Classification: H.5.2 [User Interfaces]: Input Devices and Strategies

General Terms: Human Factors

Keywords: multi-touch, touch, tactile, frustrated total internal reflection

We present a simple technique for robust multi-touch sensing at a minimum of engineering effort and expense. It is based on *frustrated total internal reflection (FTIR)*, a phenomenon familiar to both the biometric and robot sensing communities. It acquires true touch image information at high spatial and temporal resolutions, is scalable to large installations, and is well suited for use with rear-projection. It is not the aim of this paper to explore the multi-touch interaction techniques that this system enables, but rather to make the technology readily available to those who wish to do so.

RELATED WORK

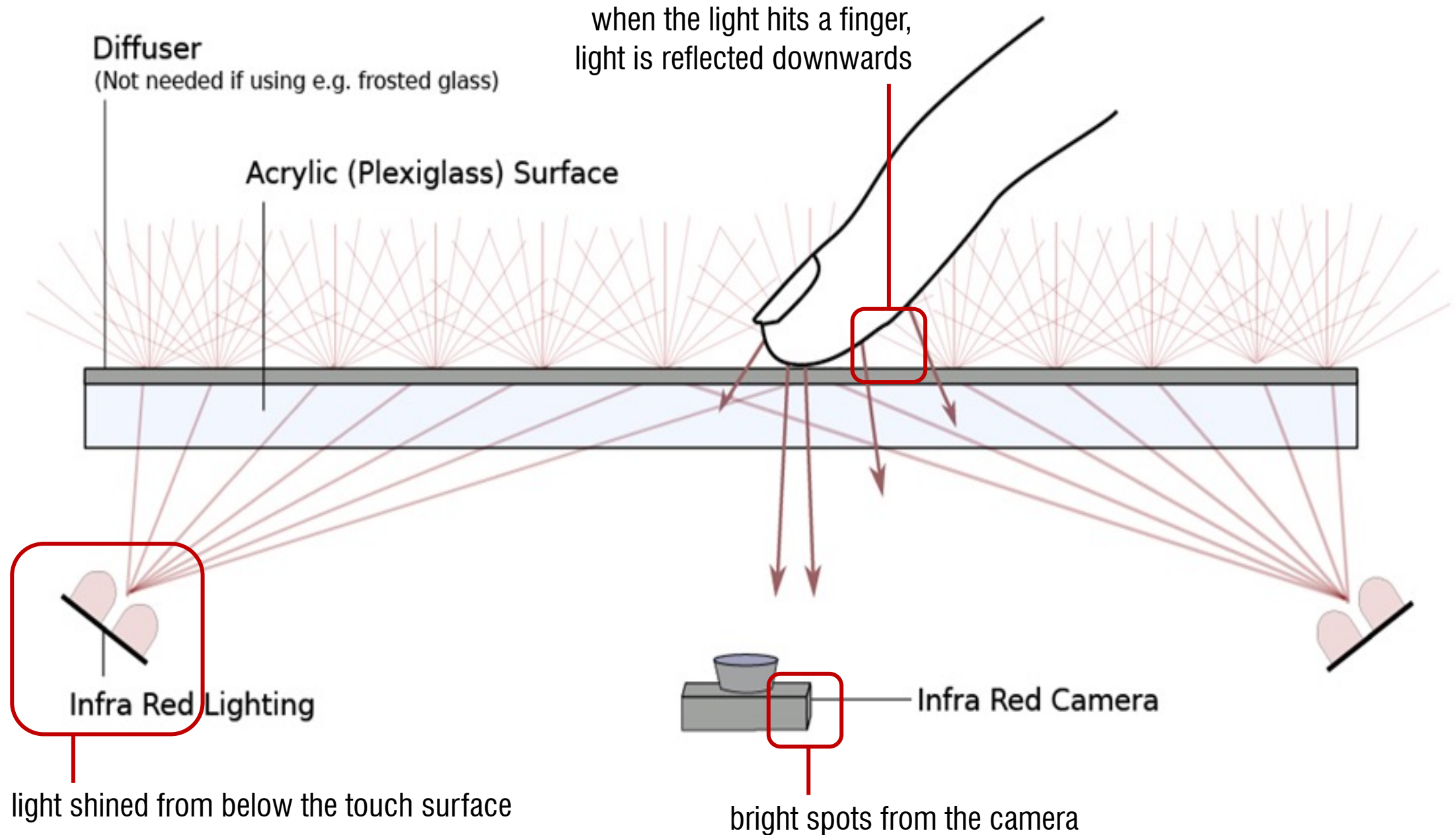
A straightforward approach to multi-touch sensing is to simply utilize a plurality of discrete sensors, making an individual connection to each sensor as in the *Tactex MTC Express* [20]. They can also be arranged in a matrix configuration with some active element (e.g. diode, transistor) at each node.

UIST 2005 paper (lasting impact award)

camera based multi-touch technology

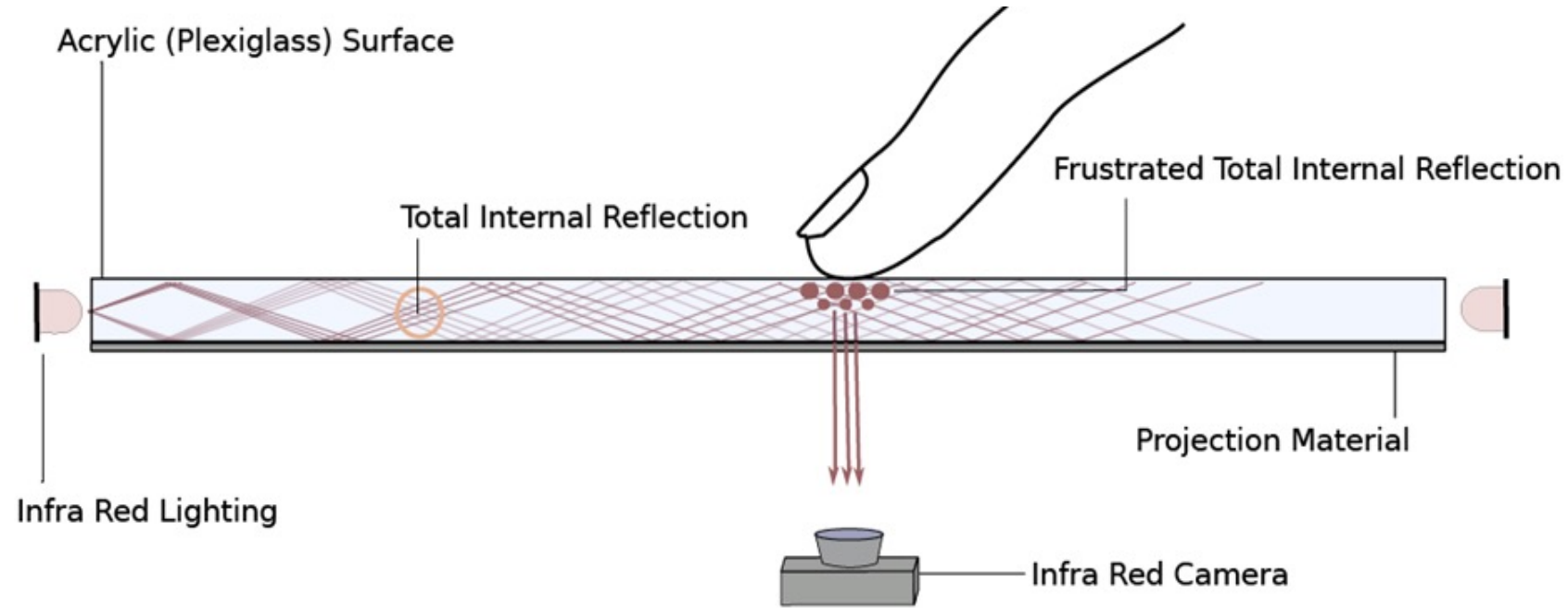
#3 - rear diffused illumination (rear DI)

RDI - Rear Diffused Illumination

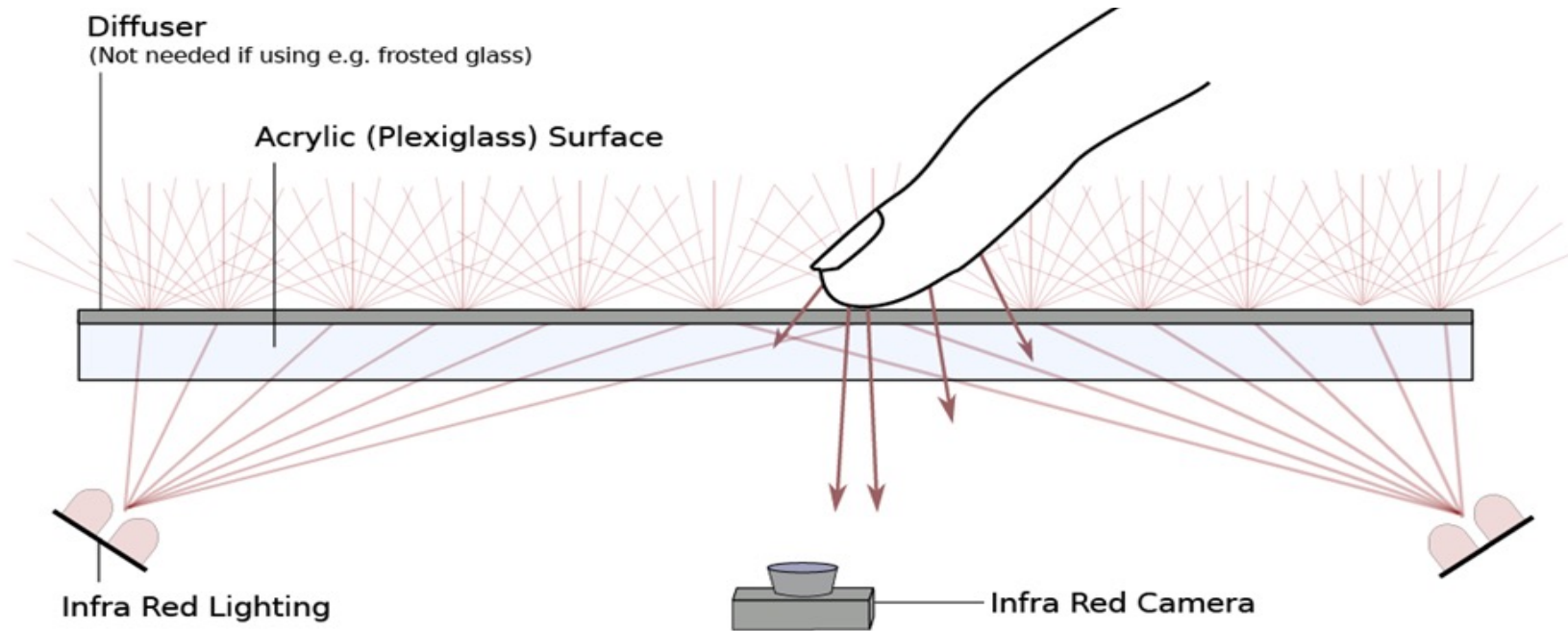


#2 - frustrated total internal reflection

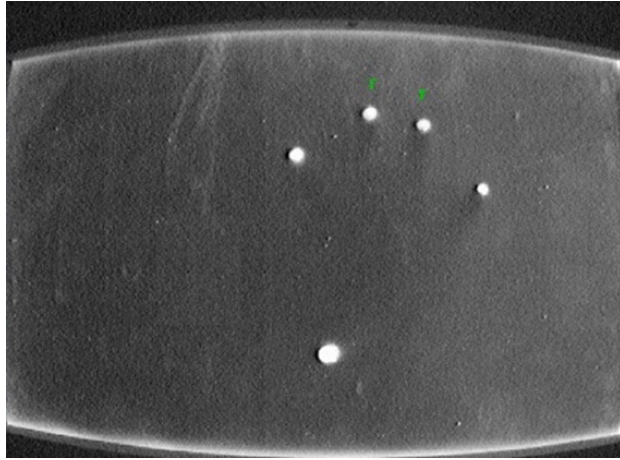
Any difference then?



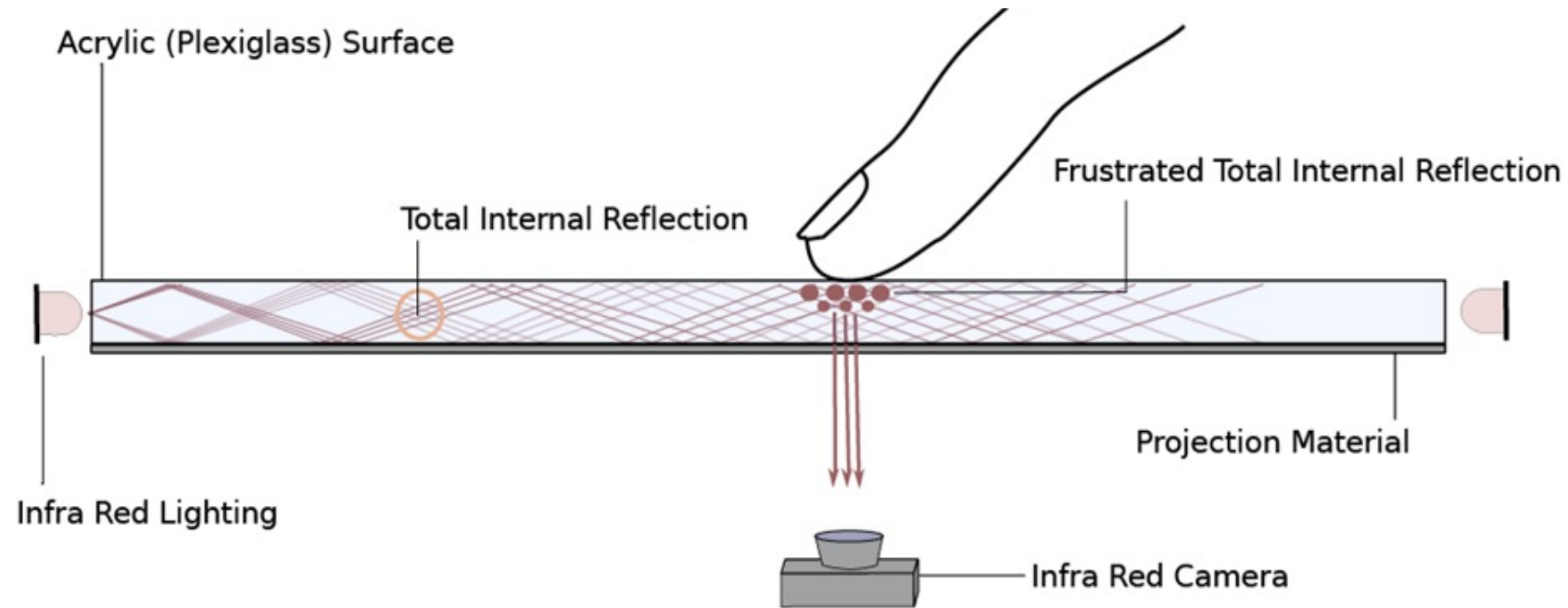
#3 - rear diffused illumination (rear DI)



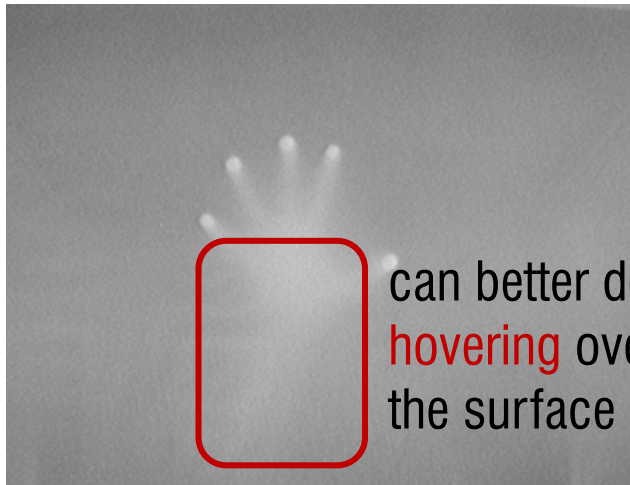
#2 - frustrated total internal reflection



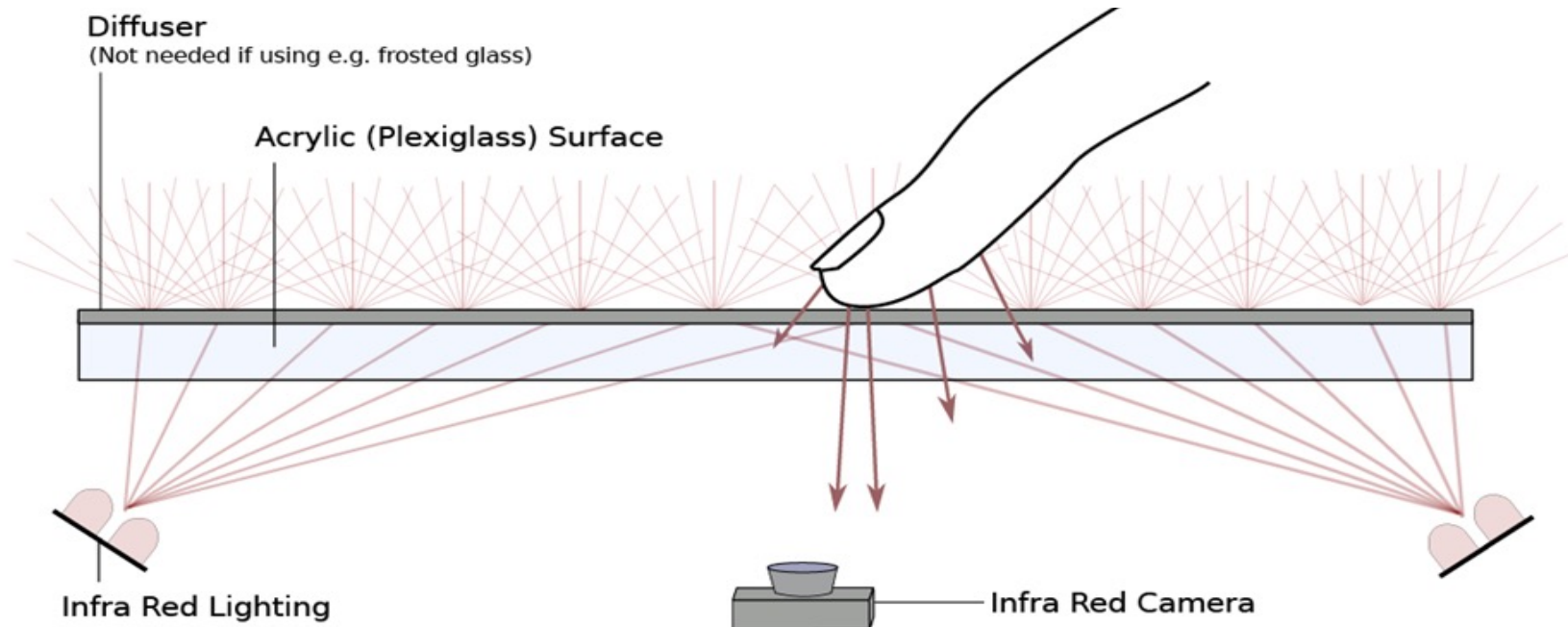
Any difference then?



#3 - rear diffused illumination (rear DI)



can better detect
hovering over
the surface



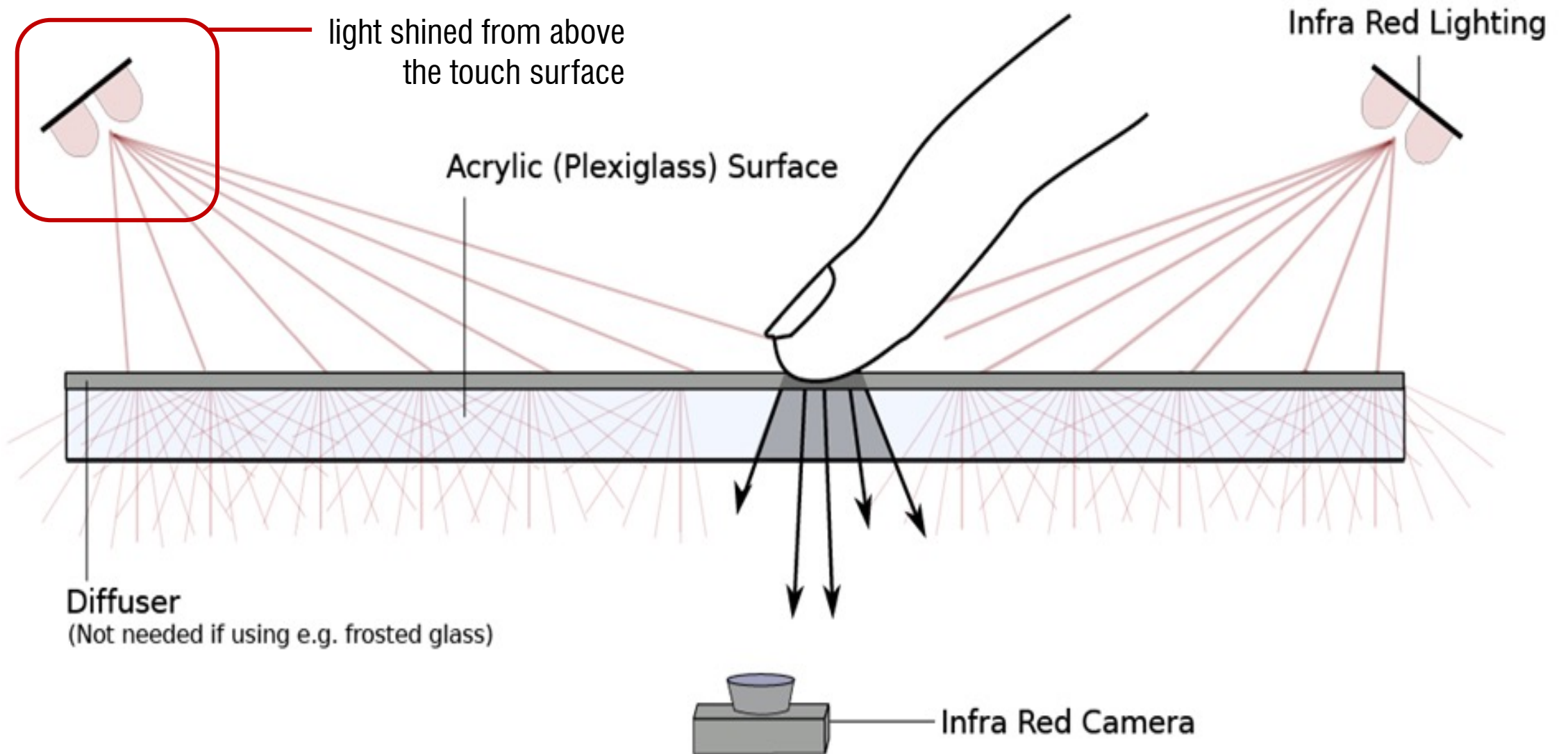
camera based multi-touch technology

#3 - rear diffused illumination (rear DI)

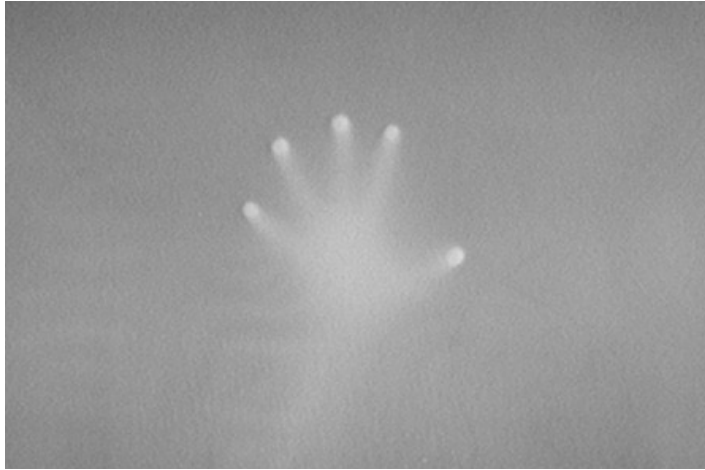
camera based multi-touch technology

#4 - front diffused illumination (front DI)

FDI - Front Diffused Illumination

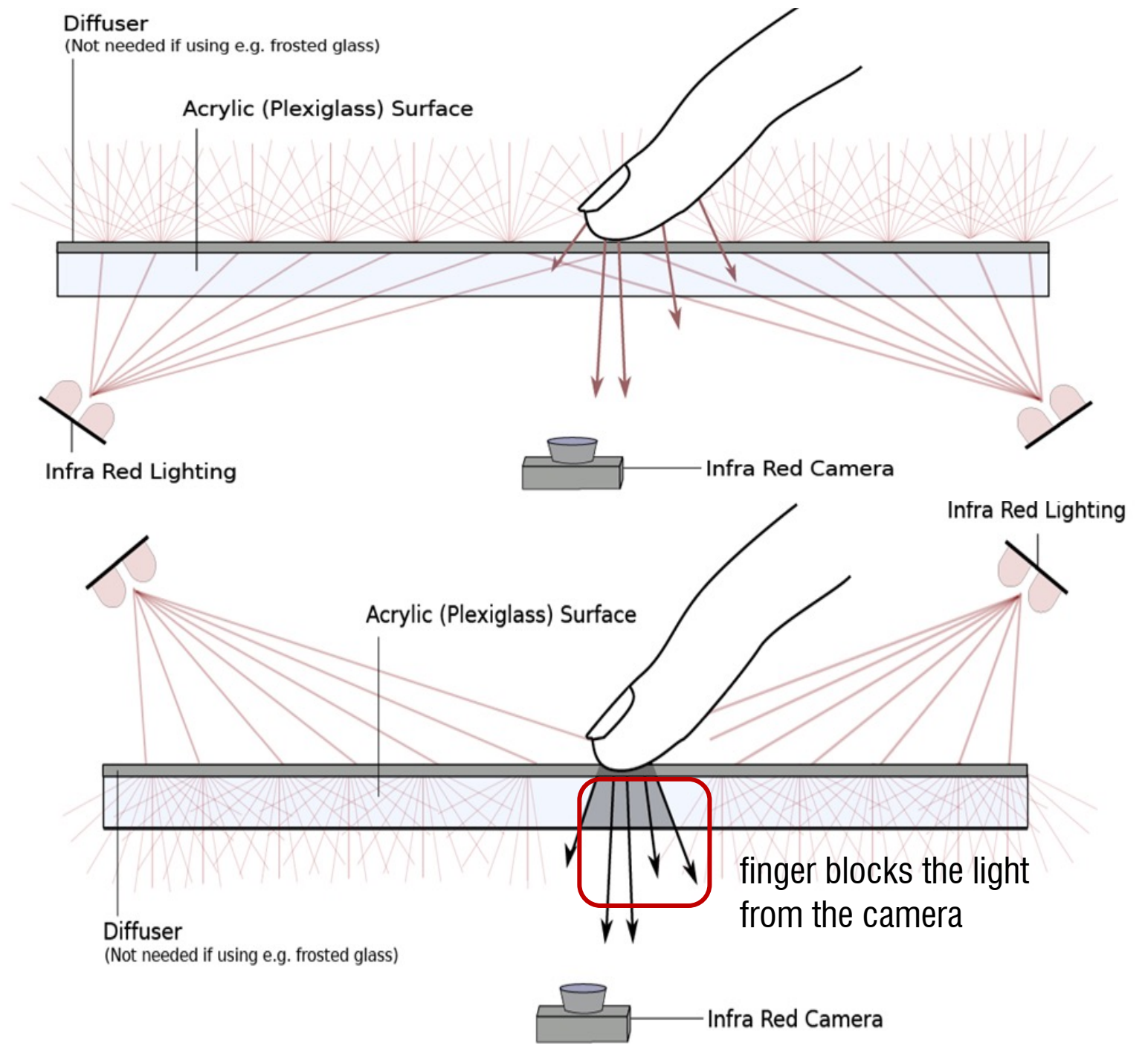
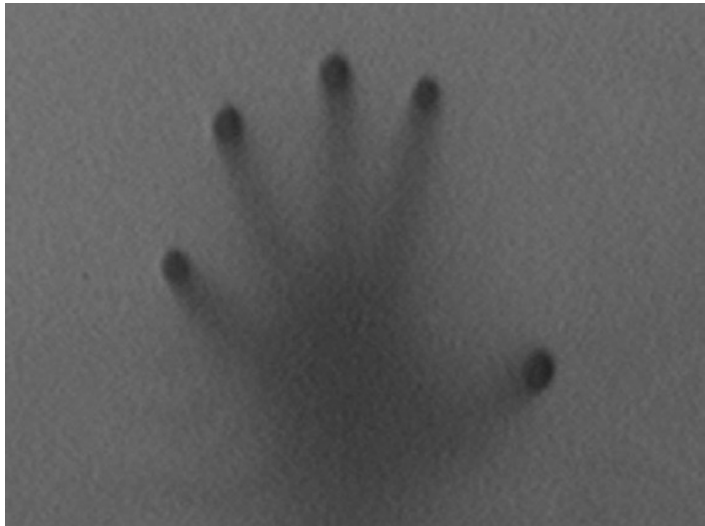


#3 - rear diffused illumination (rear DI)



Comparison?

#4 - front diffused illumination (front DI)





<http://www.youtube.com/watch?v=vLAzINB0QQY>

How to build one by yourself



camera based multi-touch technology

#1 - laser Light Plane (LLP)

#2 - frustrated total internal reflection (FTIR)

#3 - rear diffused illumination (rear DI)

#4 - front diffused illumination (front DI)

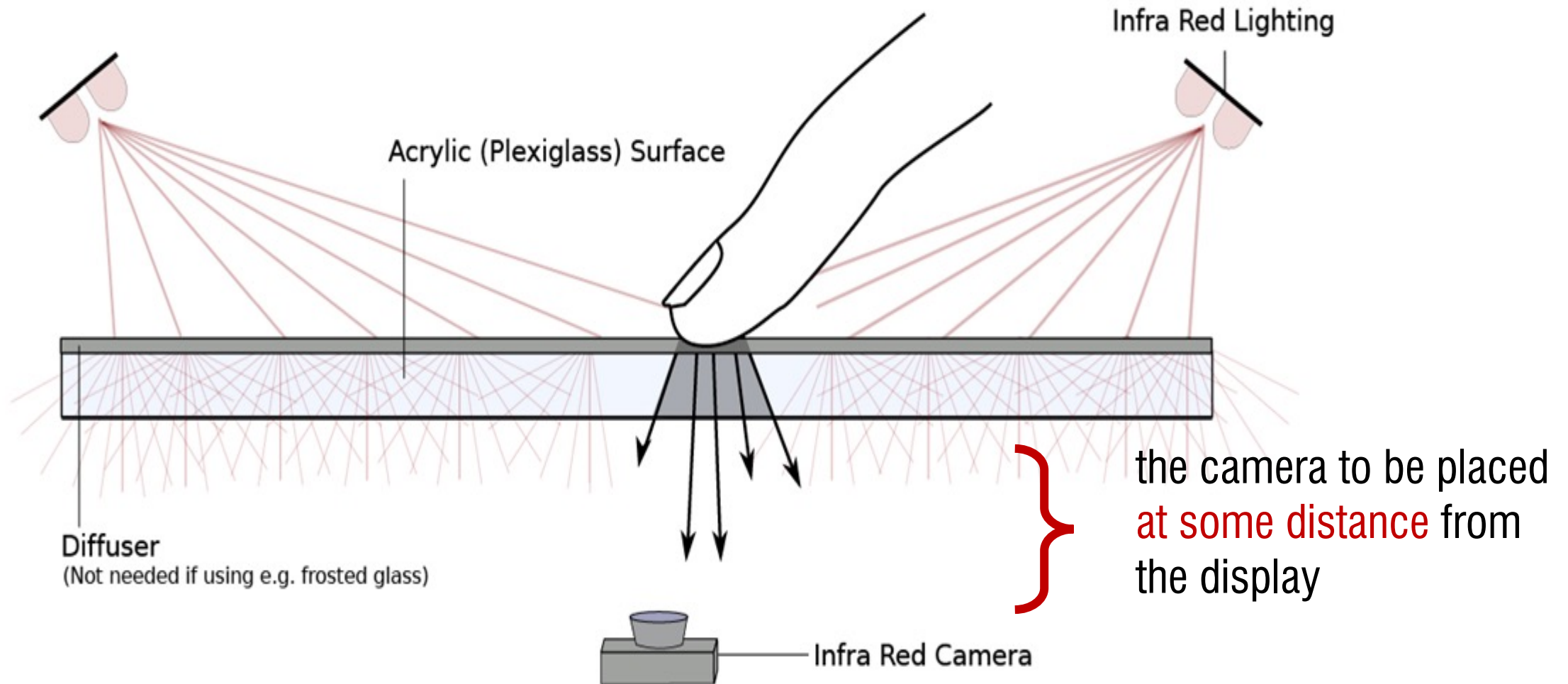
A light source

A way to break the light

A cam to capture the spot/shadow

What are the limitations of camera based multi-touch technique?

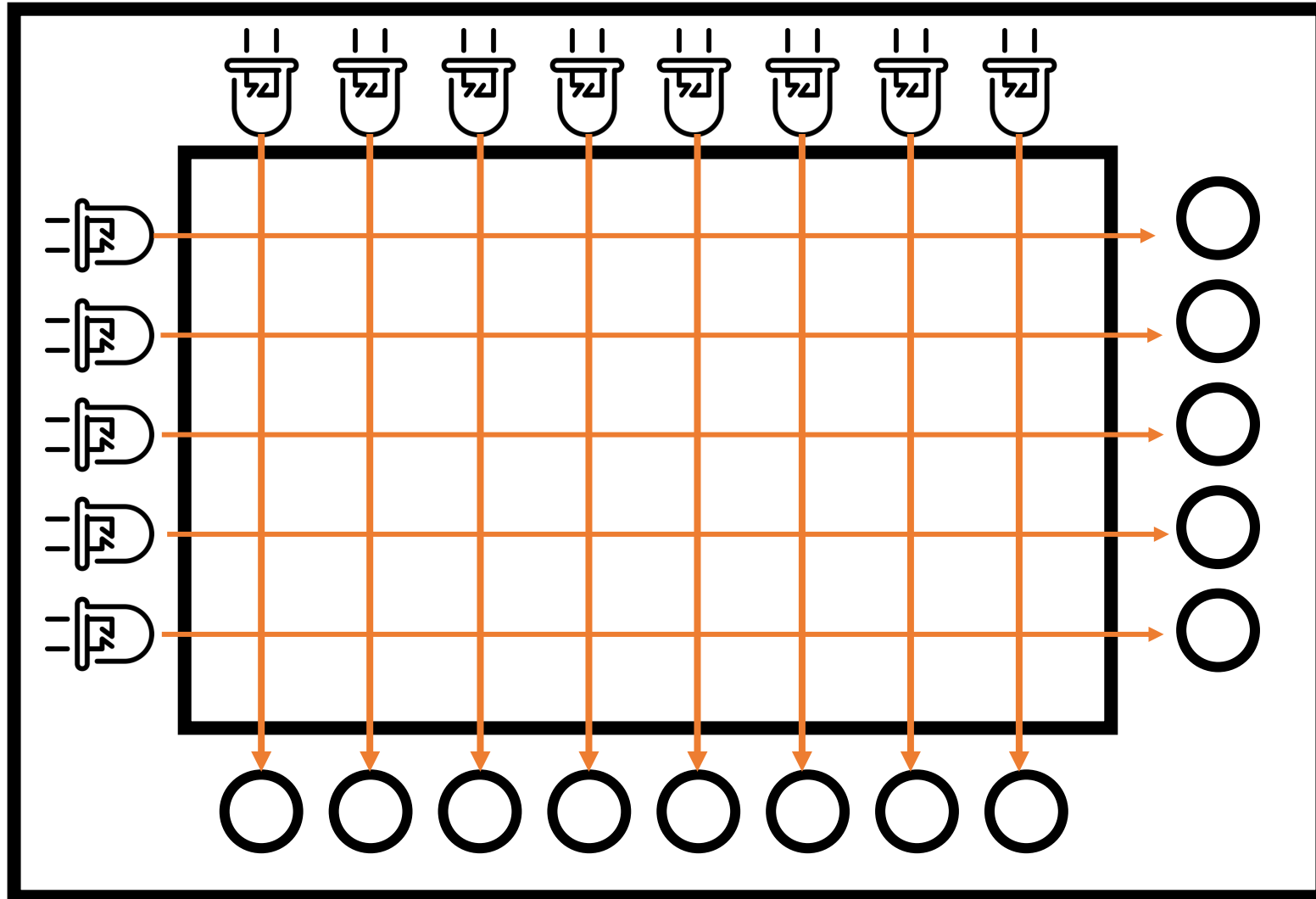
What are the limitations of camera based multi-touch technique?



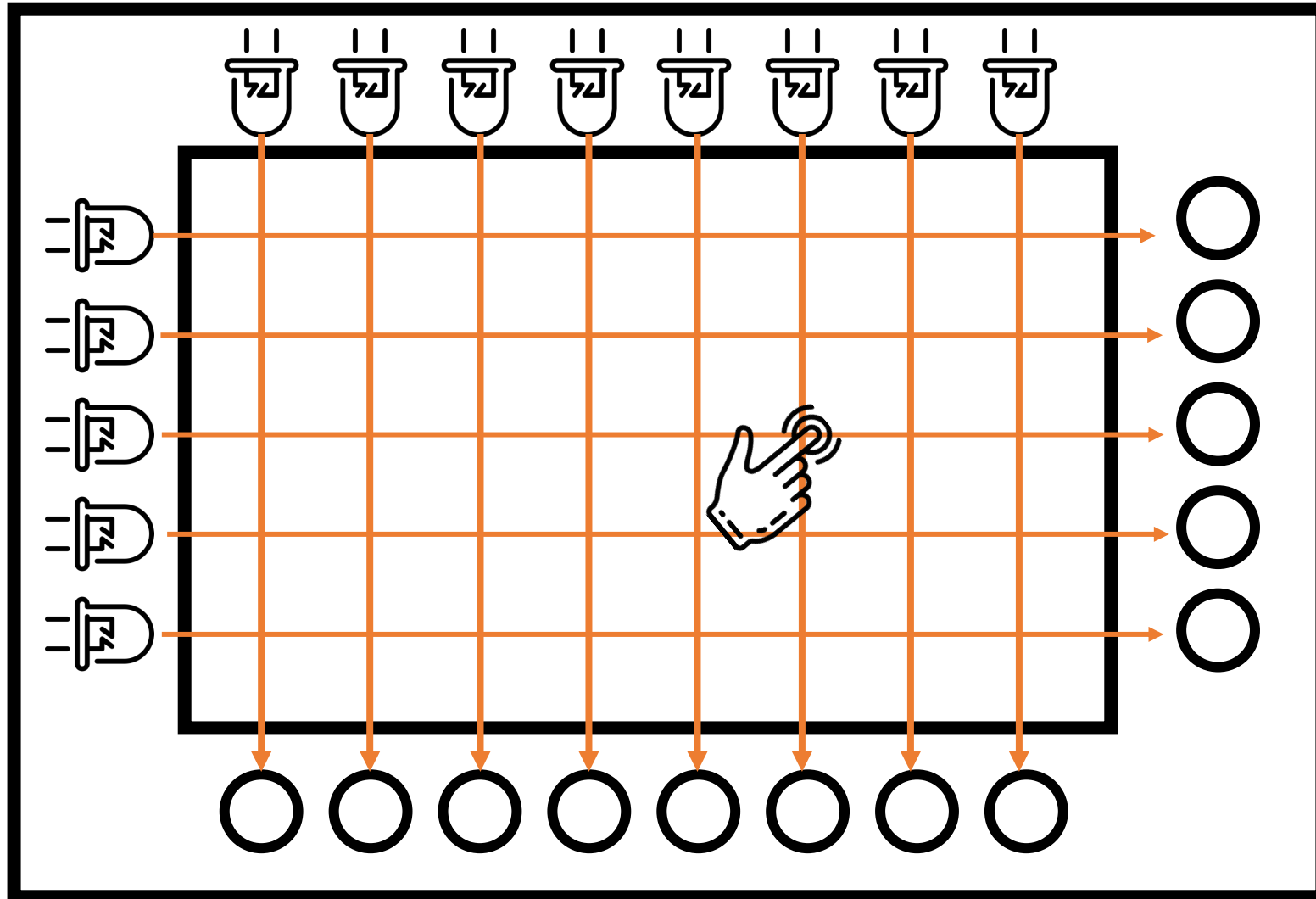
Put the sensor not to the bottom of the display
but to the side of it

infrared touch panels (ITP)

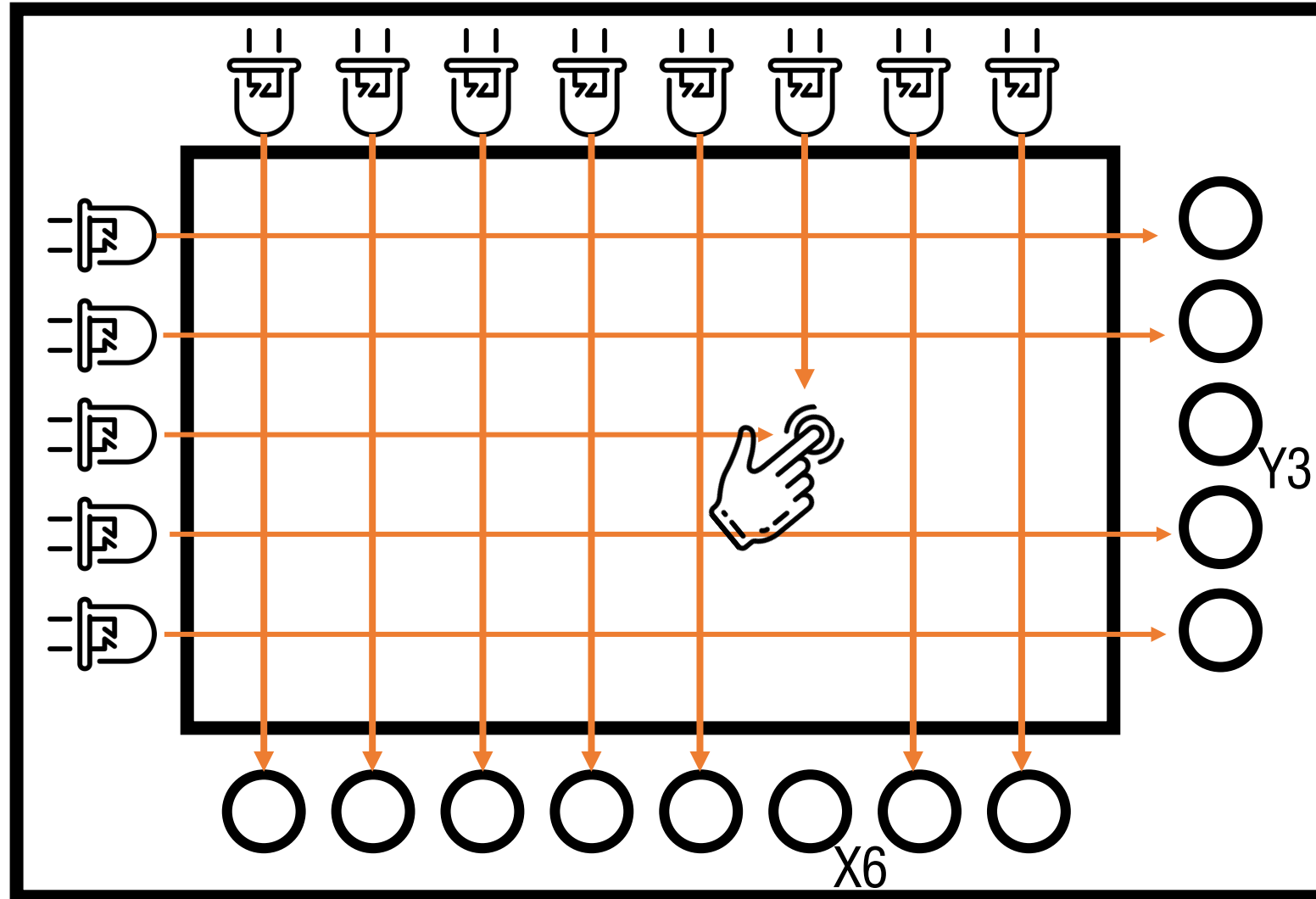
infrared touch panels (ITP)



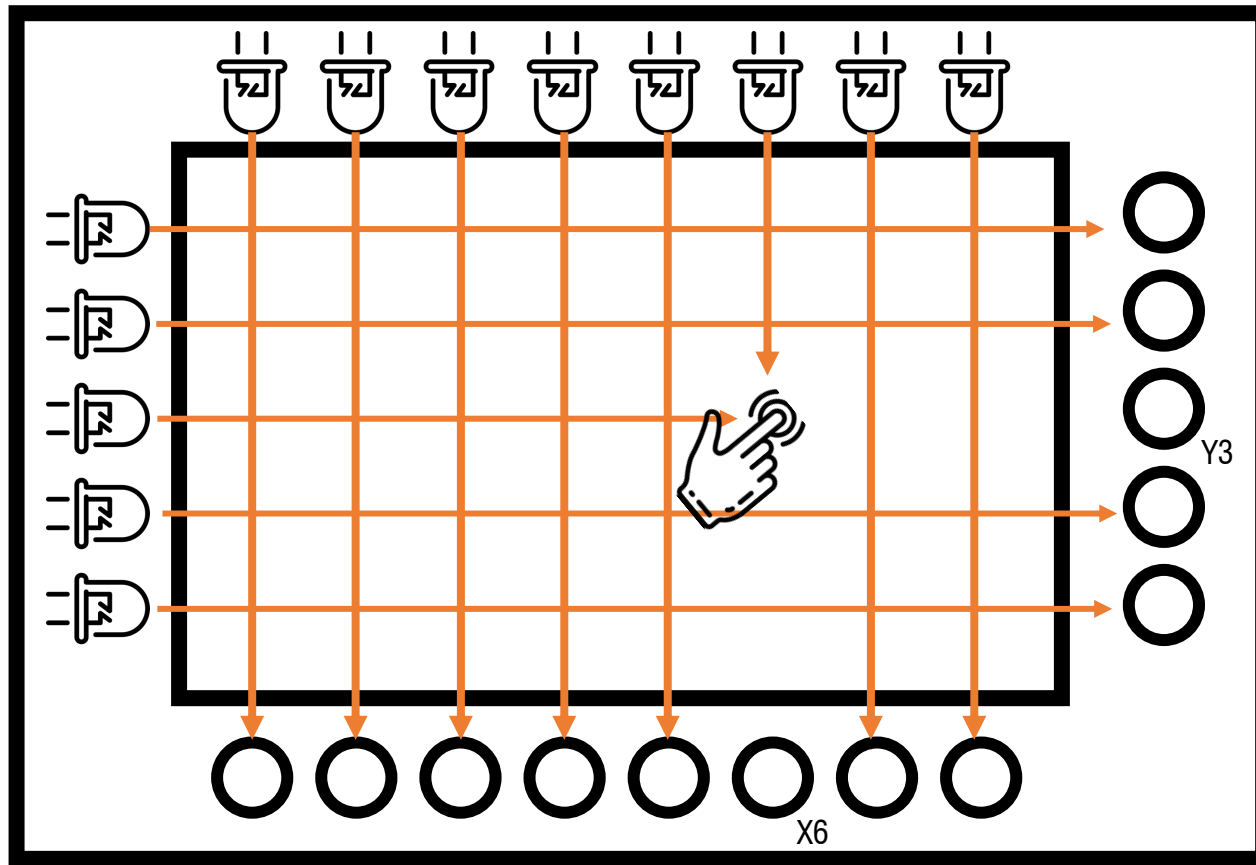
infrared touch panels (ITP)



infrared touch panels (ITP)



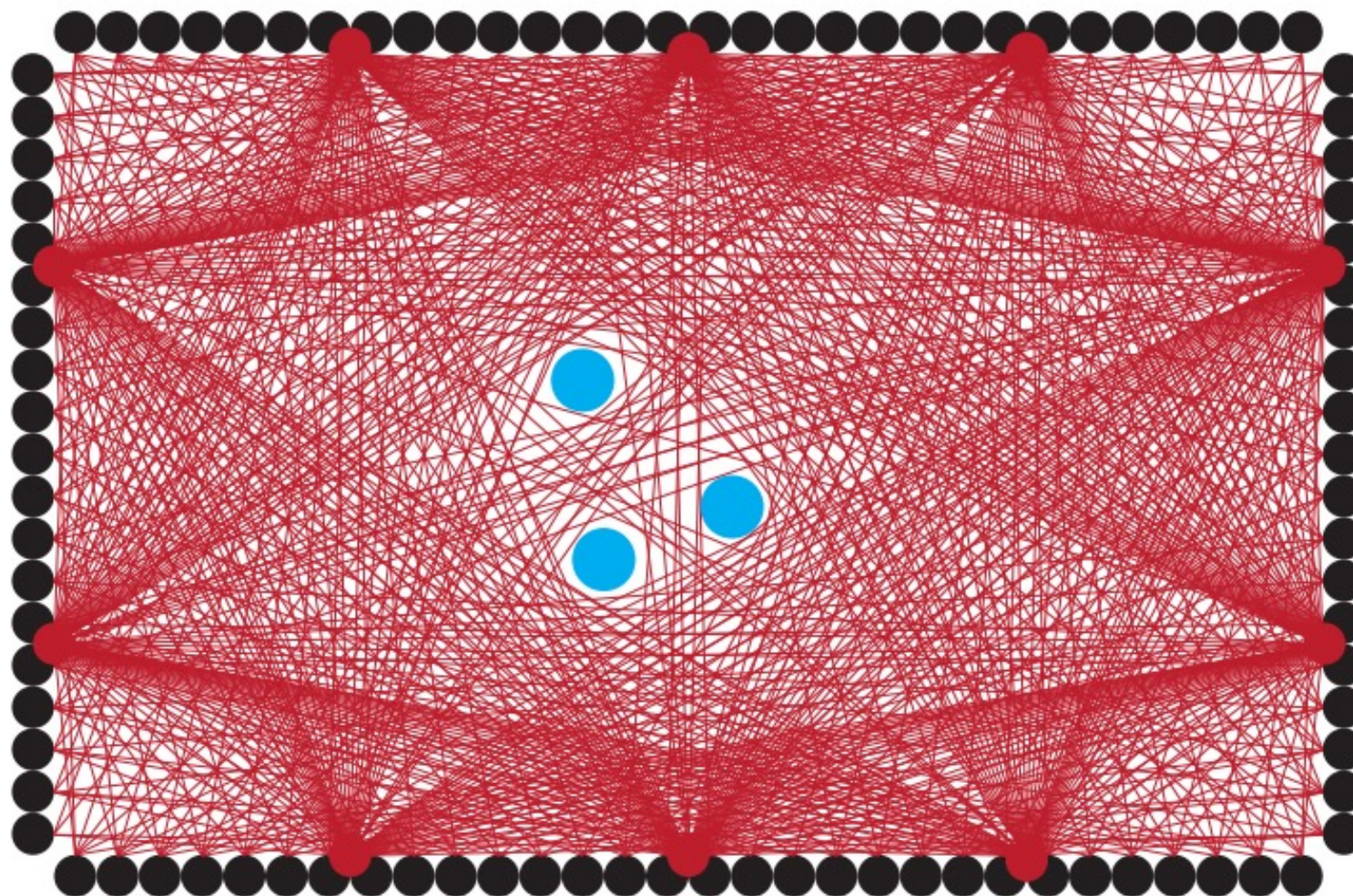
infrared touch panels (ITP)



infrared LEDs and light sensors

placed in a grid on bezel

LEDs transmit light to light sensors on the other side
anything that disrupts light, will register as touch



ZeroTouch: An Optical Multi-Touch and Free-Air Interaction Architecture

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Interface Ecology Lab @ TAMU CSE
jmoeller@gmail.com, andruid@ecologylab.net

ABSTRACT

ZeroTouch (ZT) is a unique optical sensing technique and architecture that allows precision sensing of hands, fingers, and other objects within a constrained 2-dimensional plane. ZeroTouch provides tracking at 80 Hz, and up to 30 concurrent touch points. Integration with LCDs is trivial. While designed for multi-touch sensing, ZT enables other new modalities, such as pen+touch and free-air interaction. In this paper, we contextualize ZT innovations with a review of other flat-panel sensing technologies. We present the modular sensing architecture behind ZT, and examine early diverse uses of ZT sensing.

Author Keywords

Multi-touch; ZeroTouch; Free-Air; Interaction; Sensing

ACM Classification Keywords

H.5.2 [Information Interfaces and Presentation]: User Interfaces—Input Devices

General Terms

Design, Experimentation

INTRODUCTION

Flat-panel multi-touch technologies are slowly but surely scaling to larger and larger screen-sizes. What was once predominantly the domain of bulky vision-based camera/projector multi-touch systems is now being rapidly encroached upon by more space-efficient technologies, albeit at higher relative cost/screen area.

Recent developments in large-area flat-panel multi-touch sensing have used optical technologies. Whether by incorporation of optical sensors in the display itself, or by surrounding a display with optical sensors and transmitters, optical technologies are able to scale to large screen sizes.

Capacitive sensing technologies have recently scaled to large displays, enabling high-precision multi-touch at a scale once the sole realm of vision-based sensing. However, capacitive requires factory integration, and thus

is unsuitable for integration with the large contingent of non-multi-touch displays already in the world.

There are a number of technologies that enable multi-touch interaction on non-interactive displays in the market today, and the majority of these employ optical-based touch sensing. Some use cameras and computer vision techniques, and some use optical sensors and emitters to detect touch.

In this paper, we detail ZeroTouch (ZT), a hardware/software architecture for multi-touch sensing [16]. ZeroTouch is a flat-panel optical multitouch technology using a linear array of modulated light receivers which surround the periphery of a display to detect touch. It is designed with a modular architecture. A complete sensor is built from a number of smaller sensing modules, allowing a full sensor to be built at any practical size.

First, we present an overview of flat-panel optical multi-touch techniques, and position ZeroTouch amidst the multi-touch sensing landscape. Next, we go deeper into the technology of ZT, describing its modular architecture, sensing technique, and temporal and spatial resolution characteristics of the sensor. Finally, we develop application areas of ZT with case studies. We wrap up with a discussion and implications for the technology.

OPTICAL FLAT-PANEL SENSING TECHNOLOGIES

There are a few techniques for optical flat-panel sensing, some which sense from the sides, and some which sense directly behind or within the display itself. We will discuss some issues common to all forms of optoelectronic sensing, develop an overview of prior optoelectronic techniques, and situate ZT among them.

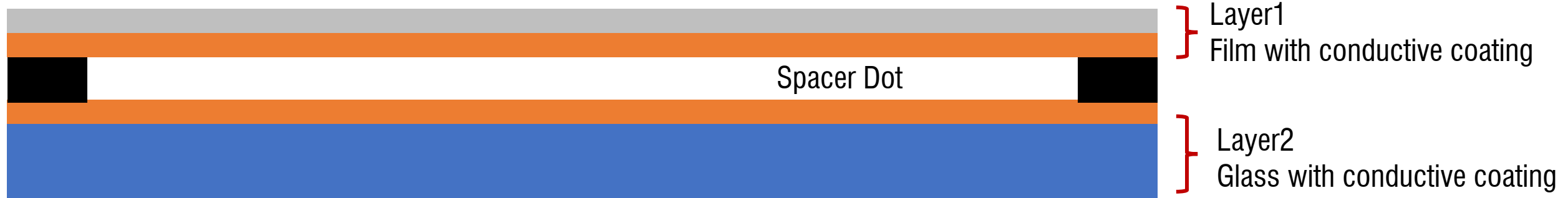
Common Issues in Optoelectronic Sensing

Among the wide variety of techniques for optoelectronic touch sensing, most suffer from a few common problems which can interfere with a system's success. Ambient light sensitivity is perhaps the most important noise factor in optoelectronic multi-touch systems, followed by active light interference.

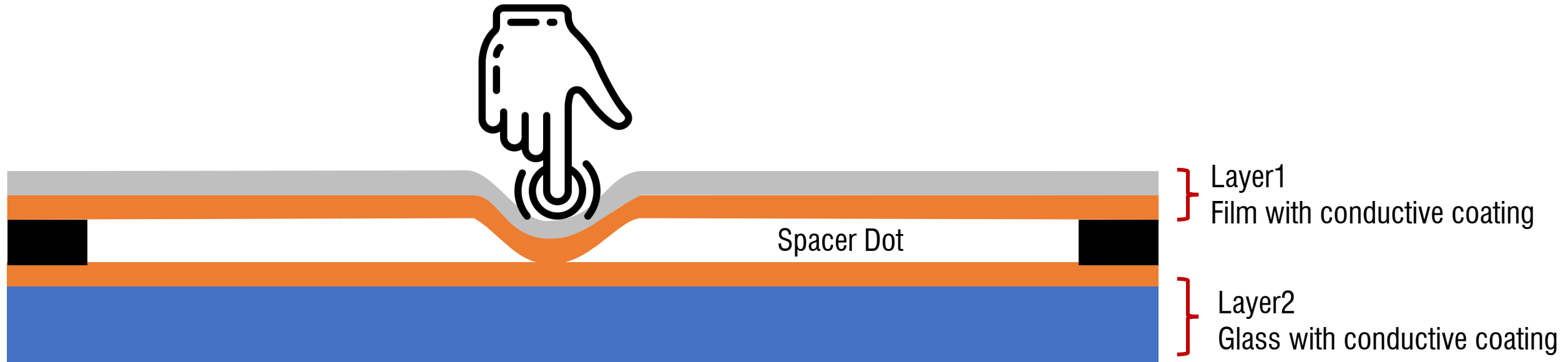
CHI 2012
Moeller et.al. from TAMU

infrared touch panels (ITP)
resistive touch panels (RTP)

resistive touch panels (RTP)



resistive touch panels (RTP)

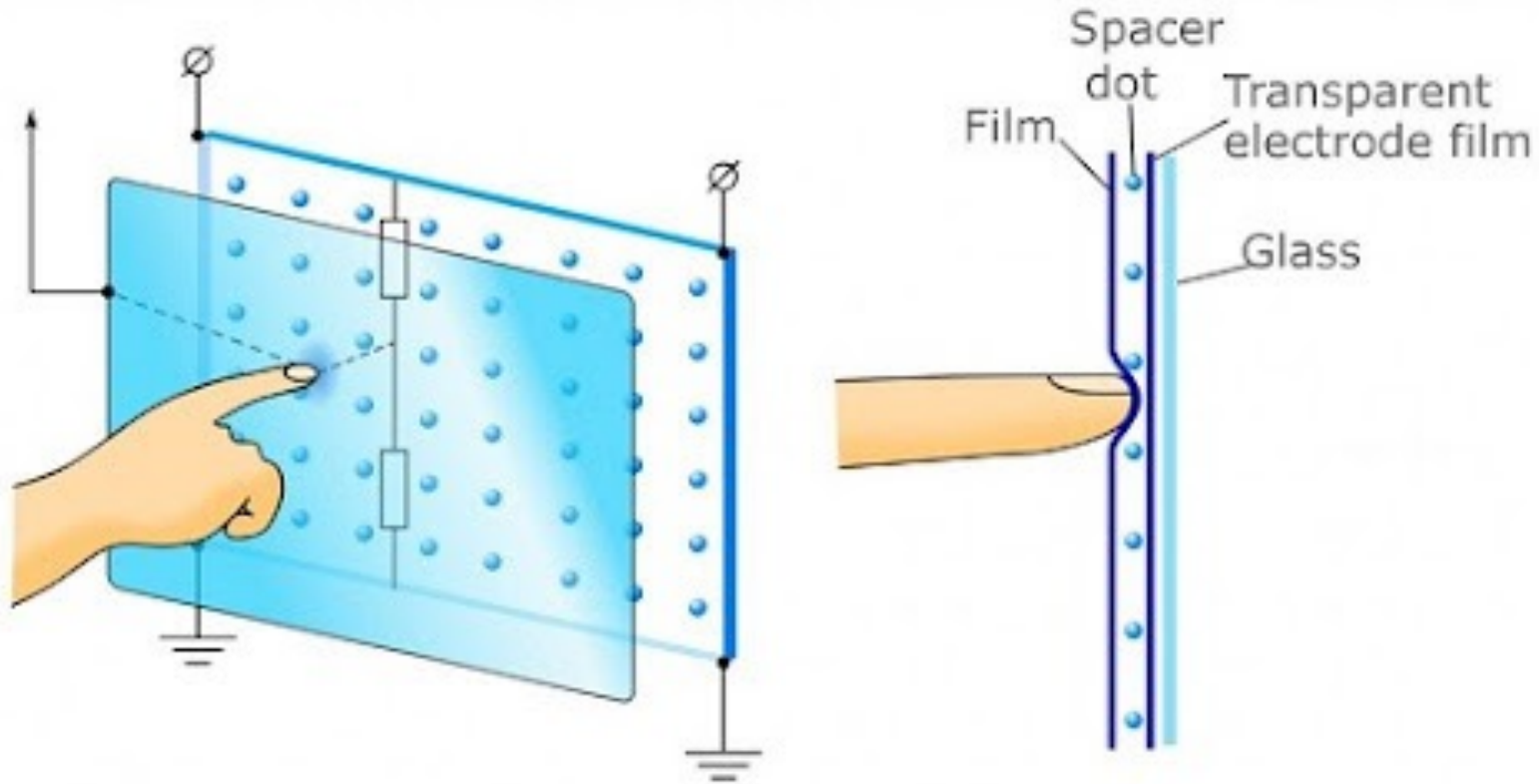


when the top sheet gets pressed by a finger, the pressed point
makes contact with the bottom sheet
electricity now get conducted at the contact point





Sensing principle?



infrared touch panels (ITP)
resistive touch panels (RTP)
capacitive touch screens

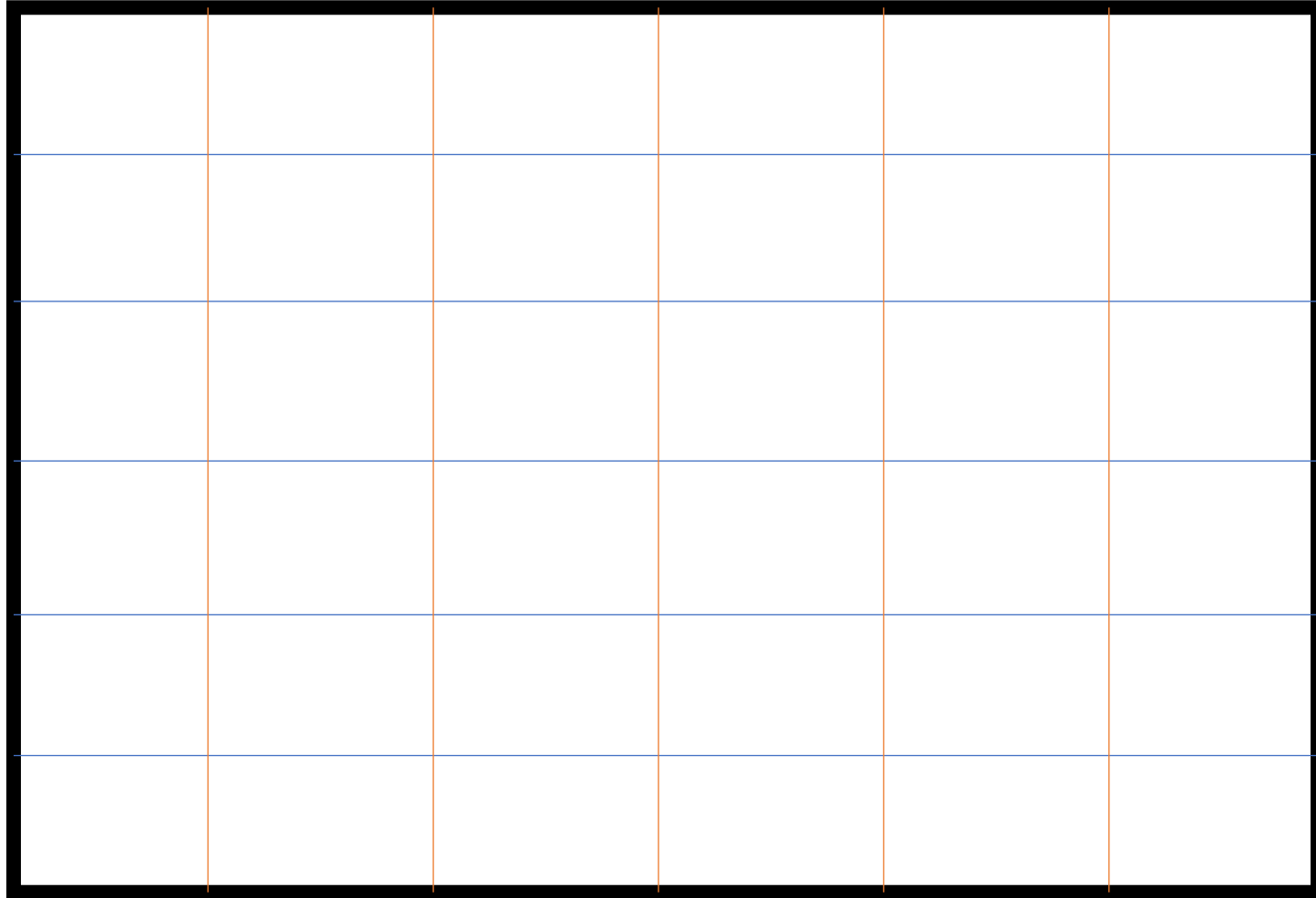
capacitive
touch screens

2007



Sensing lines
to detect
electric current

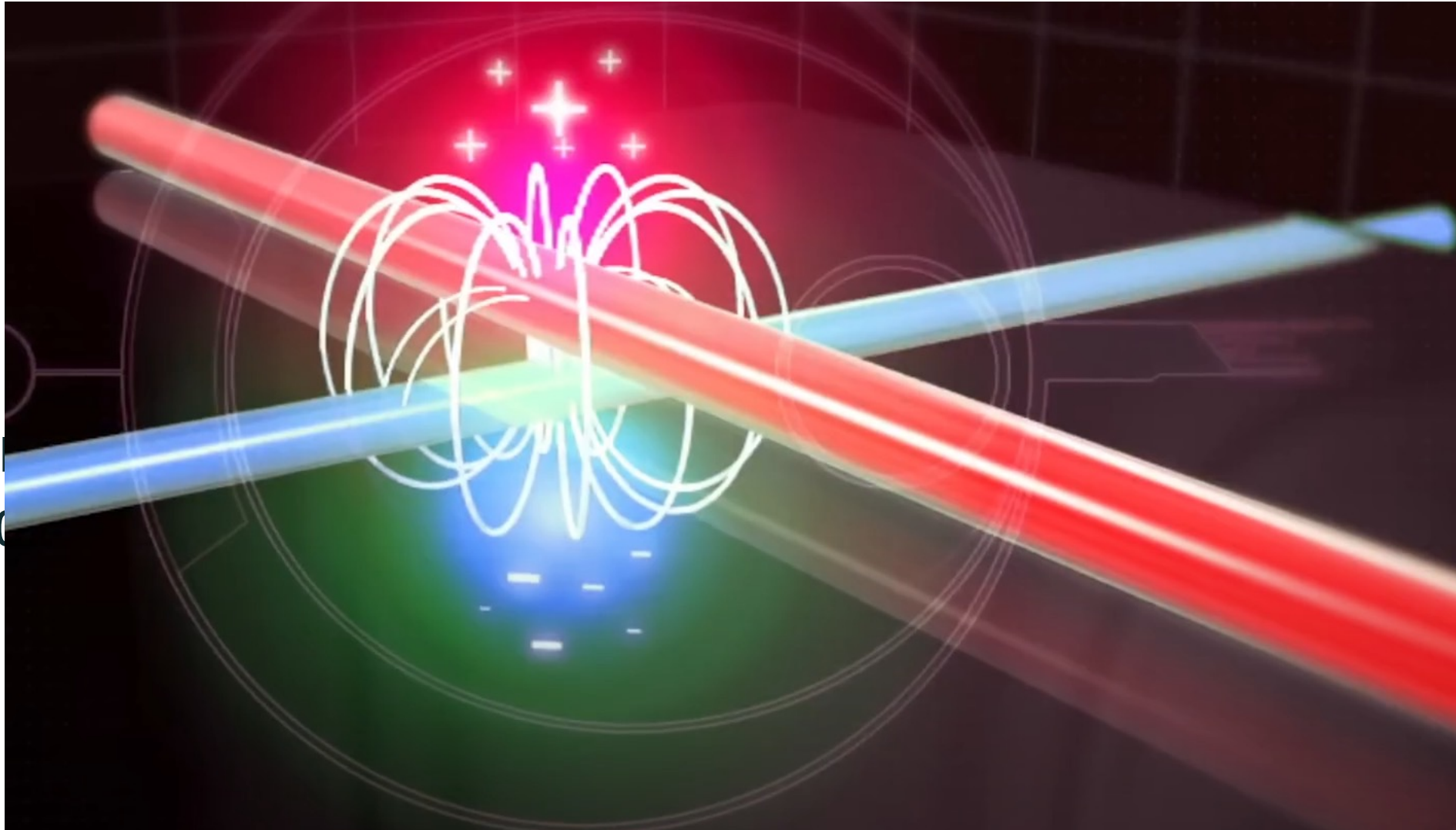
Driving lines
with constant
electric current



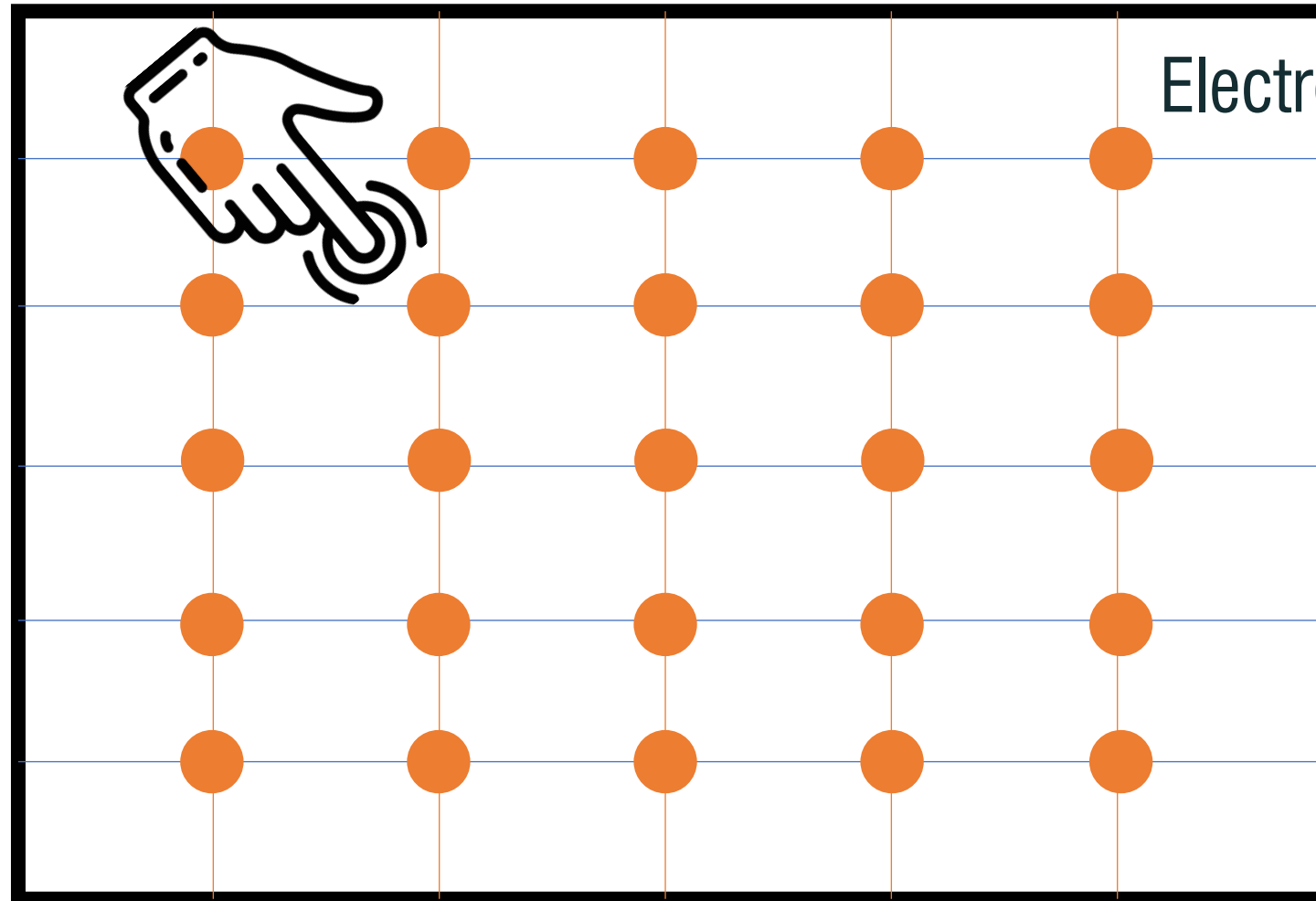
Sensing lines
to detect

ic Field

Driven
with c
electric



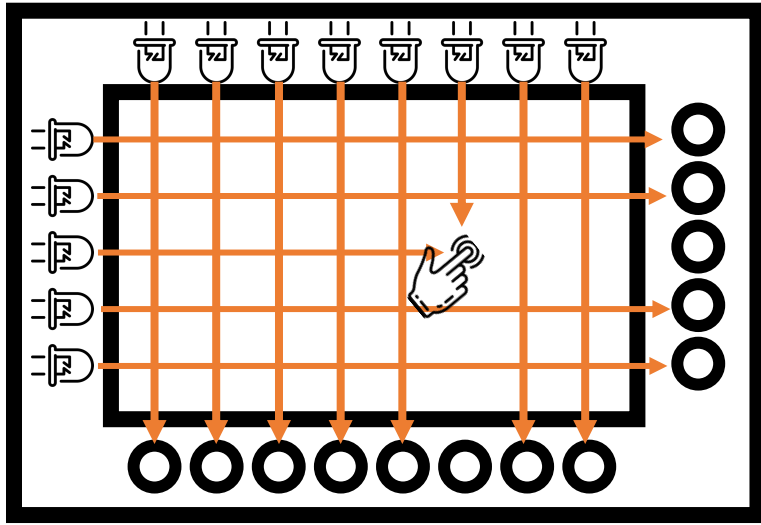
Human body has a natural capacitance
distorting the electrostatic field
at the contact point



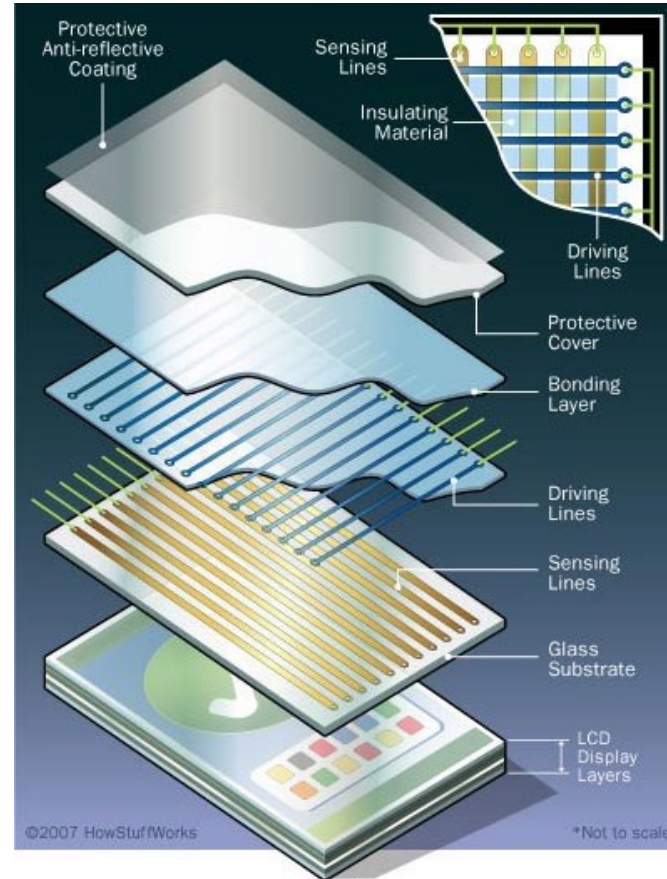
Electrostatic Field

Real touch screen
has a very high
density of the grid

infrared touch panels (ITP)

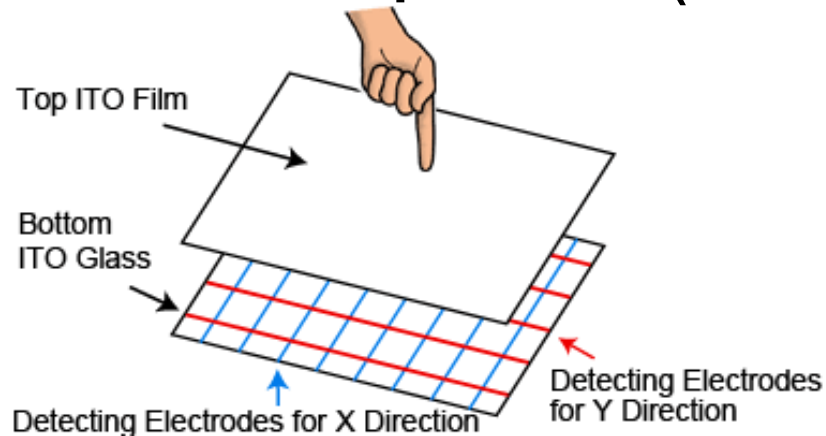


capacitive touch screens

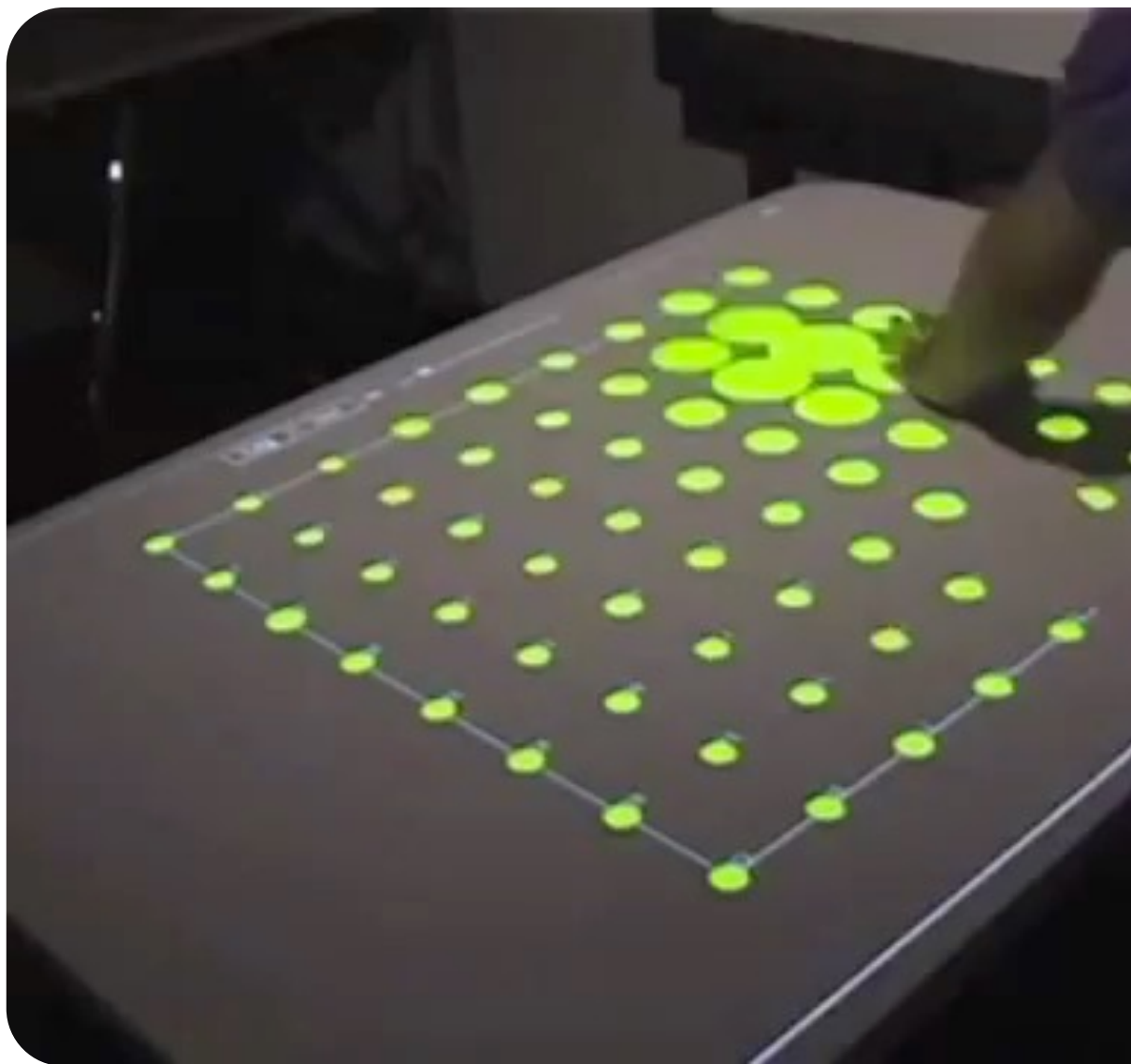


same principle

resistive touch panels (RTP)



<http://www.sky-technology.eu/en/displays/touch-screens/projected-capacitive-touch-screens-how-they-work.html>



minneapolis, minnesota, usa • 20-25 april 2002

Paper: Two-Handed Interaction

SmartSkin: An Infrastructure for Freehand Manipulation on Interactive Surfaces

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<http://www.csl.sony.co.jp/person/rekimoto.html>

ABSTRACT

This paper introduces a new sensor architecture for making interactive surfaces that are sensitive to human hand and finger gestures. This sensor recognizes multiple hand positions and shapes and calculates the distance between the hand and the surface by using capacitive sensing and a mesh-shaped antenna. In contrast to camera-based gesture recognition systems, all sensing elements can be integrated within the surface, and this method does not suffer from lighting and occlusion problems. This paper describes the sensor architecture, as well as two working prototype systems: a table-size system and a tablet-size system. It also describes several interaction techniques that would be difficult to perform without using this architecture.



Figure 1: An interactive surface system based on the

CHI 2002
Jun Rekimoto

DiamondTouch

A Multi-User Touch Technology

DiamondTouch: A Multi-User Touch Technology

Paul Dietz and Darren Leigh
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ABSTRACT

A technique for creating a touch-sensitive input device is proposed which allows multiple, simultaneous users to interact in an intuitive fashion. Touch location information is determined independently for each user, allowing each touch on a common surface to be associated with a particular user. The surface generates location dependent, modulated electric fields which are capacitively coupled through the users to receivers installed in the work environment. We describe the design of these systems and their applications. Finally, we present results we have obtained with a small prototype device.

KEYWORDS: DiamondTouch, multi-user, touch, collaborative input, single display groupware

INTRODUCTION

DiamondTouch is a multi-user touch technology for tabletop front-projected displays. It enables several different people to use the same touch-surface simultaneously without interfering with each other, or being affected by foreign objects. It also allows the computer to identify which person is touch-

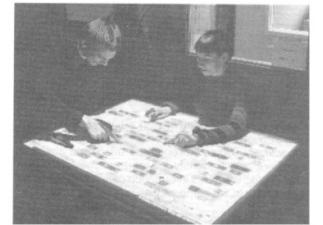


Figure 1: The collaborative work environment for Human-Guided Simple Search.

ity. Keeping track of many mice is nearly impossible. This leaves users physically pointing at their virtual pointers to

UIST 2001
Dietz et.al.

Learn the technologies behind multi-touch screen

Camera-based | Resistive | Capacitive | ...

Recap

technologies behind multi-touch screen

Camera-based | Resistive | Capacitive | ...

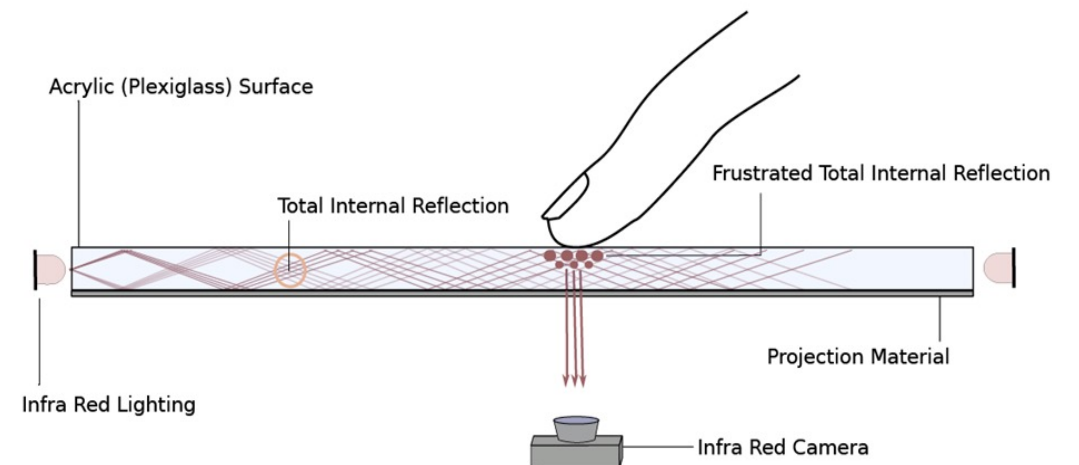
#1 - laser Light Plane (LLP)

#2 - frustrated total internal reflection (FTIR)

#3 - rear diffused illumination (rear DI)

#4 - front diffused illumination (front DI)

FTIR - Frustrated Total Internal Reflection



Recap

technologies behind multi-touch screen

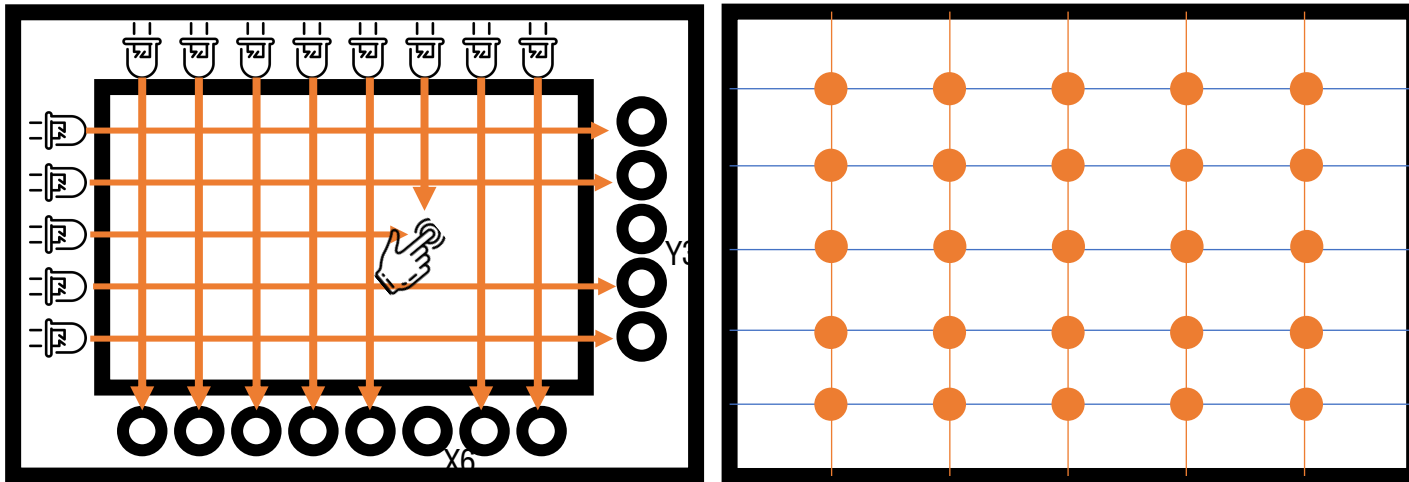
Camera-based | Resistive | Capacitive | ...



Recap

technologies behind multi-touch screen

Camera-based | Resistive | Capacitive | ...



We have seen touchscreen devices almost everywhere nowadays replacing physical buttons



What can we do
for people who
cannot benefit
from it?





BrushLens

Hardware Interaction Proxies for Accessible Touchscreen Interface Actuation

Chen Liang, Yasha Iravantchi, Thomas Krolkowski, Ruijie Geng
Alanson Sample, Anhong Guo



BrushLens: Hardware Interaction Proxies for Accessible Touchscreen Interface Actuation

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Ann Arbor, MI, USA
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Anhong Guo
University of Michigan
Ann Arbor, MI, USA
anhong@umich.edu



Figure 1: Touchscreen devices are widely adopted but not always accessible, such as restaurant kiosks (1). Assumptions about users' visual and motor abilities (2) to perceive visual information, locate, navigate, interpret interface layout, and precisely perform pre-defined gestures do not always hold, making devices inaccessible for some users. We propose BrushLens, a hardware phone case (3) that is equipped with an array of touchscreen actuators (4). It acts as a hardware interaction proxy that perceives, locates, and actuates touchscreen on behalf of users (5), and allows users to interpret and give interaction intentions through the accessible interface running on their personal devices. This allows users to "Brush" on the interface (6) while the actuators constantly monitor their positions through camera and sensor input, and perform a touch gesture directly if any of them is on top of the target button, making inaccessible devices accessible for people with diverse abilities.

ABSTRACT

Touchscreen devices, designed with an assumed range of user abilities and interaction patterns, often present challenges for individuals with diverse abilities to operate independently. Prior efforts to improve accessibility through tools or algorithms necessitated alterations to touchscreen hardware or software, making them in-applicable for the large number of existing legacy devices. In this paper, we introduce BrushLens, a hardware interaction proxy that performs physical interactions on behalf of users while allowing them to continue utilizing accessible interfaces, such as screenreaders and assistive touch on smartphones, for interface exploration and command input. BrushLens maintains an interface model for accurate target localization and utilizes exchangeable actuators for physical actuation across a variety of device types, effectively reducing user workload and minimizing the risk of mistouch. Our evaluations reveal that BrushLens lowers the mistouch rate and

empowers visually and motor impaired users to interact with otherwise inaccessible physical touchscreens more effectively.

KEYWORDS

Touchscreen appliances, accessibility, interaction proxy, computer vision, touch actuation

ACM Reference Format:
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1 INTRODUCTION

Touchscreen devices have become ubiquitous in everyday life, playing a critical role in performing various everyday tasks. From flight check-in kiosks to food ordering systems, interacting with these devices independently has become essential in various usage scenarios. However, despite their widespread adoption, such devices are often designed with assumptions about users' abilities and interaction patterns, making them less accessible to completely inaccessible for users with diverse abilities. Individuals with visual impairments may have difficulty perceiving the necessary information to operate these touchscreens, and the risk of triggering unintended actions

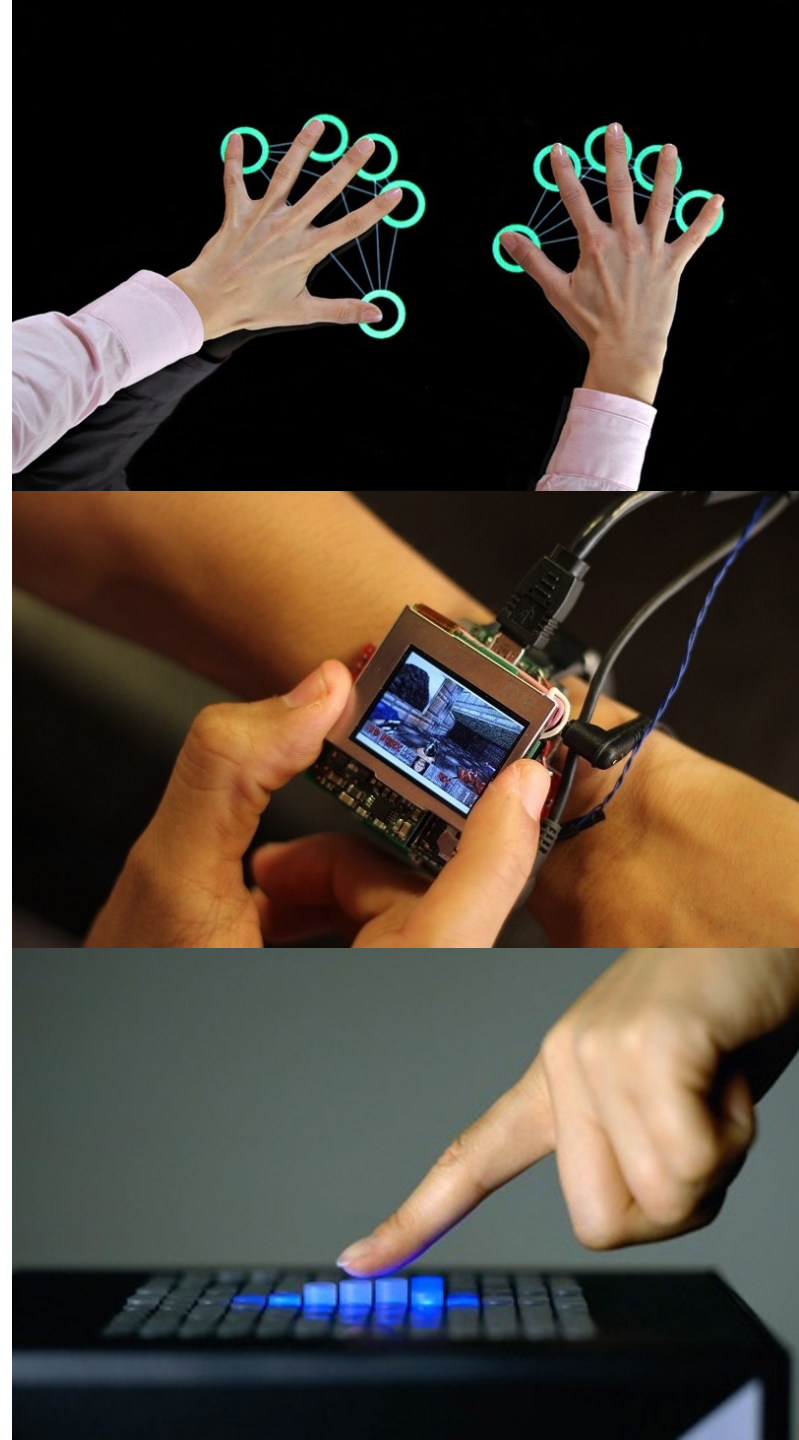
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DiamondTouch: A Multi-User Touch Technology

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ABSTRACT

A technique for creating a touch-sensitive input device is proposed which allows multiple, simultaneous users to interact in an intuitive fashion. Touch location information is determined independently for each user, allowing each touch on a common surface to be associated with a particular user. The surface generates location dependent, modulated electric fields which are capacitively coupled through the users to receivers installed in the work environment. We describe the design of these systems and their applications. Finally, we present results we have obtained with a small prototype device.

KEYWORDS: DiamondTouch, multi-user, touch, collaborative input, single display groupware

INTRODUCTION

DiamondTouch is a multi-user touch technology for tabletop front-projected displays. It enables several different people to use the same touch-surface simultaneously without interfering with each other, or being affected by foreign objects. It also allows the computer to identify which person is touching where.

During the course of research on Human-Guided Simple Search [1] some of our colleagues have constructed a collaborative workspace in which multiple users work on the same data set. The environment consists of a ceiling-mounted video projector displaying onto a white table around which the users sit. A single wireless mouse is passed around as different users take the initiative. Our colleagues proposed that the collaboration would be improved if the users could independently and simultaneously interact with the table, and considered using multiple mice.

The use of multiple mice in a collaborative environment is particularly problematic. It can be challenging for users to keep track of one pointer on a large surface with lots of activ-

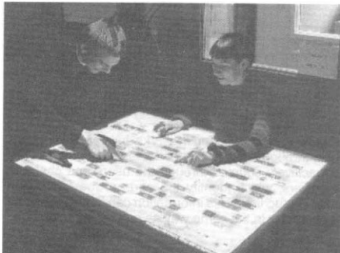


Figure 1: The collaborative work environment for Human-Guided Simple Search.

ity. Keeping track of many mice is nearly impossible. This leaves users physically pointing at their virtual pointers to tell other users where they are. Also, relying on a separate physical device keeps us from utilizing the natural human tendencies of reaching, touching and grasping.¹

Using a large touch-screen as the table surface would seem to be an answer, but existing touch technologies were inadequate. Most allow only a single touch and do not identify users. While schemes have been developed where users take turns [3], we wanted the interaction to be simultaneous and spontaneous.

Unlike electronic whiteboards or other vertical touch systems, the tabletop nature of our display creates a problem: people tend to put things on tables. With a pressure-sensitive surface, foreign objects create spurious touch-points causing single touch systems to malfunction.

Optimally, we would like a multi-user touch surface to have the following characteristics:

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¹ Plus see the discussion in [2] for advantages of touch tablets over mice.

StateLens: A Reverse Engineering Solution for Making Existing Dynamic Touchscreens Accessible

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ABSTRACT

Blind people frequently encounter inaccessible dynamic touchscreens in their everyday lives that are difficult, frustrating, and often impossible to use independently. Touchscreens are often the only way to control everything from coffee machines and payment terminals, to subway ticket machines and in-flight entertainment systems. Interacting with dynamic touchscreens is difficult non-visually because the visual user interfaces change, interactions often occur over multiple different screens, and it is easy to accidentally trigger interface actions while exploring the screen. To solve these problems, we introduce *StateLens* — a three-part reverse engineering solution that makes existing dynamic touchscreens accessible. First, *StateLens* reverse engineers the underlying state diagrams of existing interfaces using point-of-view videos found online or taken by users using a hybrid crowd-computer vision pipeline. Second, using the state diagrams, *StateLens* automatically generates conversational agents to guide blind users through specifying the tasks that the interface can perform, allowing the *StateLens* iOS application to provide interactive guidance and feedback so that blind users can access the interface. Finally, a set of 3D-printed accessories enable blind people to explore capacitive touchscreens without the risk of triggering accidental touches on the interface. Our technical evaluation shows that *StateLens* can accurately reconstruct interfaces from stationary, hand-held, and web videos; and, a user study of the complete system demonstrates that *StateLens* successfully enables blind users to access otherwise inaccessible dynamic touchscreens.

Author Keywords

Reverse engineering; dynamic interfaces; touchscreen appliances; accessibility; crowdsourcing; computer vision; conversational agents.

CCS Concepts

•Human-centered computing → Interactive systems and tools; Accessibility technologies;

INTRODUCTION

Inaccessible touchscreen interfaces in the world represent a long-standing and frustrating problem for people who are

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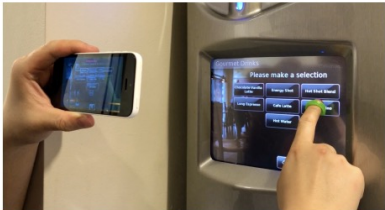
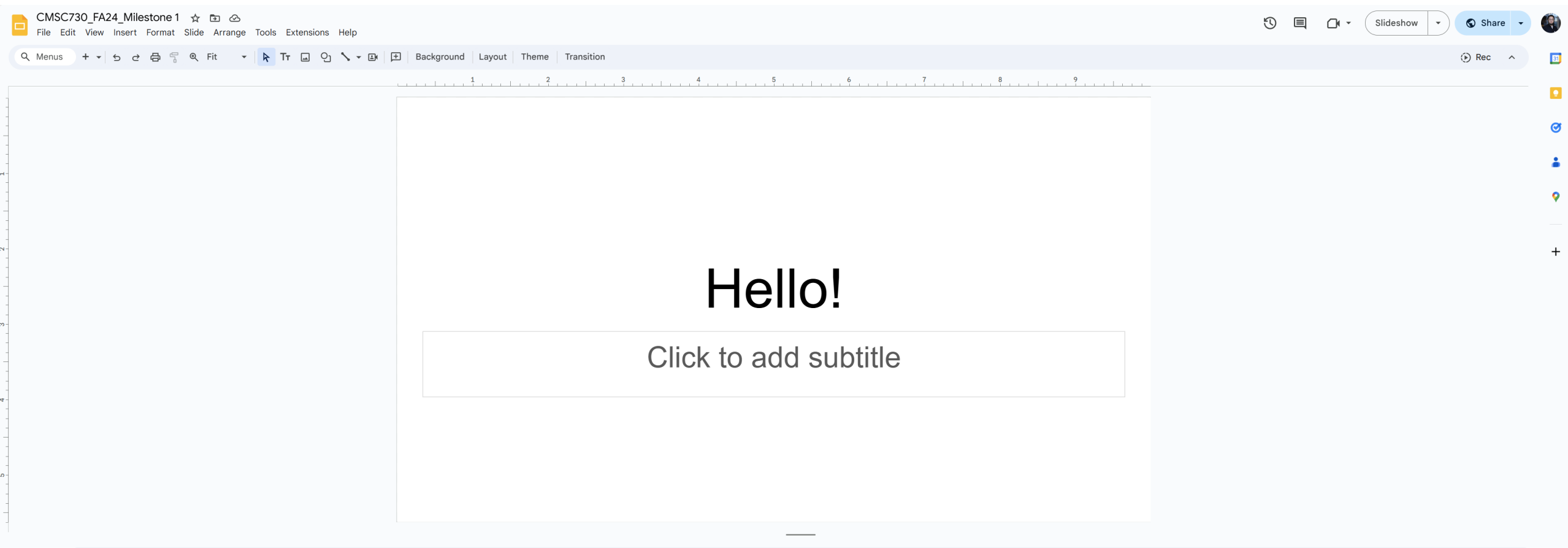


Figure 1. *StateLens* is a system that enables blind users to interact with touchscreen devices in the real world by (i) reverse engineering a structured model of the underlying interface, and (ii) using the model to provide interactive conversational and audio guidance to the user about how to use it. A set of 3D-printed accessories enable capacitive touchscreens to be used non-visually by preventing accidental touches on the interface.

blind. Imagine sitting down for a 12-hour flight only to realize that the entertainment center on the seatback in front of you can only be controlled by its inaccessible touchscreen; imagine checking out at the grocery store and being required to tell the cashier your pin number out loud because the checkout kiosk is an inaccessible touchscreen; and, imagine not being able to independently make yourself a coffee at your workplace because the fancy new coffee machine is controlled only by an inaccessible touchscreen. Such frustrating accessibility problems are commonplace and pervasive.

Making touchscreen interfaces accessible has been a long-standing challenge in accessibility [14, 17, 30], and some current platforms are quite accessible (e.g., iOS). Solving all of the challenges represented by the combination of difficult issues for public touchscreen devices has remained elusive: (i) touchscreens are inherently visual so a blind person cannot read what they say or identify user interface components, (ii) a blind person cannot touch the touchscreen to explore without the risk of accidentally triggering something they did not intend, and, (iii) a blind person does not have the option to choose a different touchscreen platform that would be more accessible and cannot get access to the software or hardware to make it work better. This paper is about enabling blind people to use the touchscreens they encounter *in-the-wild*, despite the fact that nothing about how these systems are designed is intended for their use.

Most prior work on making touchscreens accessible has assumed access to change or add to the touchscreen hardware or software. For example, physical buttons were added to the



<https://shorturl.at/D88YK>